

Introduction to Marko Chain Monte Carlo

Meaningful Modeling of Epidemiologic Data, 2016
AIMS, Muizenberg, South Africa

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Bayes Theorem

\cap denotes "and"

$|$ denotes "given"

Bayesian Statistics

$$P(\text{model} \mid \text{data}) = \frac{P(\text{data} \mid \text{model}) P(\text{model})}{P(\text{data})}$$

$$\text{posterior} = \frac{\text{likelihood} \times \text{prior}}{P(\text{data})}$$

By “model”, we often mean a specific model parameterization

Bayesian Statistics

$$P(\text{parameters} \mid \text{data}) = \frac{P(\text{data} \mid \text{parameters}) P(\text{parameters})}{P(\text{data})}$$

$$\text{posterior} = \frac{\text{likelihood} \times \text{prior}}{P(\text{data})}$$

Bayesian Statistics

$$P(\theta \mid y) = \frac{P(y \mid \theta) P(\theta)}{P(y)}$$

$$\text{posterior} = \frac{\text{likelihood} \times \text{prior}}{P(y)}$$

What is $P(y)$?

$$P(y) = \int P(y \mid \theta) P(\theta) d\theta$$

Probability of observing y marginal over all possible values of θ .

Bayesian Statistics

$$P(\theta | y) = \frac{P(y | \theta) P(\theta)}{P(y)}$$

$$\text{posterior} = \frac{\text{likelihood} \times \text{prior}}{P(y)}$$

What is $P(y)$?

$$P(y) = \int \text{likelihood} \times \text{prior } d\theta$$

Probability of observing y marginal over all possible values of θ .

Bayesian Statistics

$$P(\theta \mid y) = \frac{P(y \mid \theta) P(\theta)}{P(y)}$$

$$\text{posterior} = \frac{\text{likelihood} \times \text{prior}}{\int \text{likelihood} \times \text{prior } d\theta}$$

Denominator is a scalar number, but rarely has an analytical solution.

Very difficult to calculate in practice!

How can we calculate posterior without denominator?

Bayesian Statistics

$$P(\theta | y) \propto P(y | \theta) P(\theta)$$

posterior \propto likelihood \times prior

The posterior is proportional to the numerator up to some scalar constant.

We also know that the posterior integrates to 1 because it is a PDF.

$$\int P(\theta | y) d\theta = 1$$

Bayesian Statistics

$$P(\theta | y) \propto P(y | \theta) P(\theta)$$

posterior \propto likelihood \times prior

For a specified model world,

the posterior distribution of θ is based on

observations y & our prior beliefs about θ .

Motivating MCMC

Want to calculate the posterior but can't do it directly because of the troublesome denominator integral.

However, we do know the following:

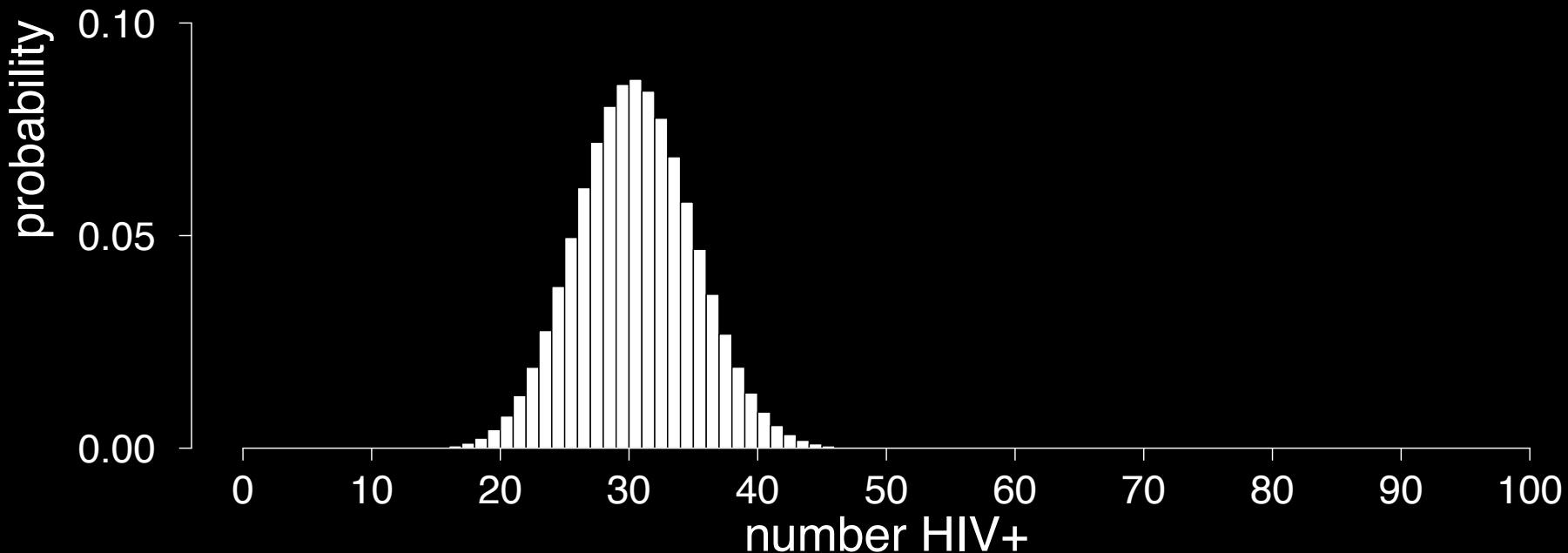
$$P(\theta \mid y) \propto P(y \mid \theta) P(\theta)$$

$$\int P(\theta \mid y) d\theta = 1$$

MCMC takes advantage of these two items to numerically approximate the posterior

In a population of 1,000,000 people with a true prevalence of 30%, the probability distribution of number of positive individuals if 100 are sampled:

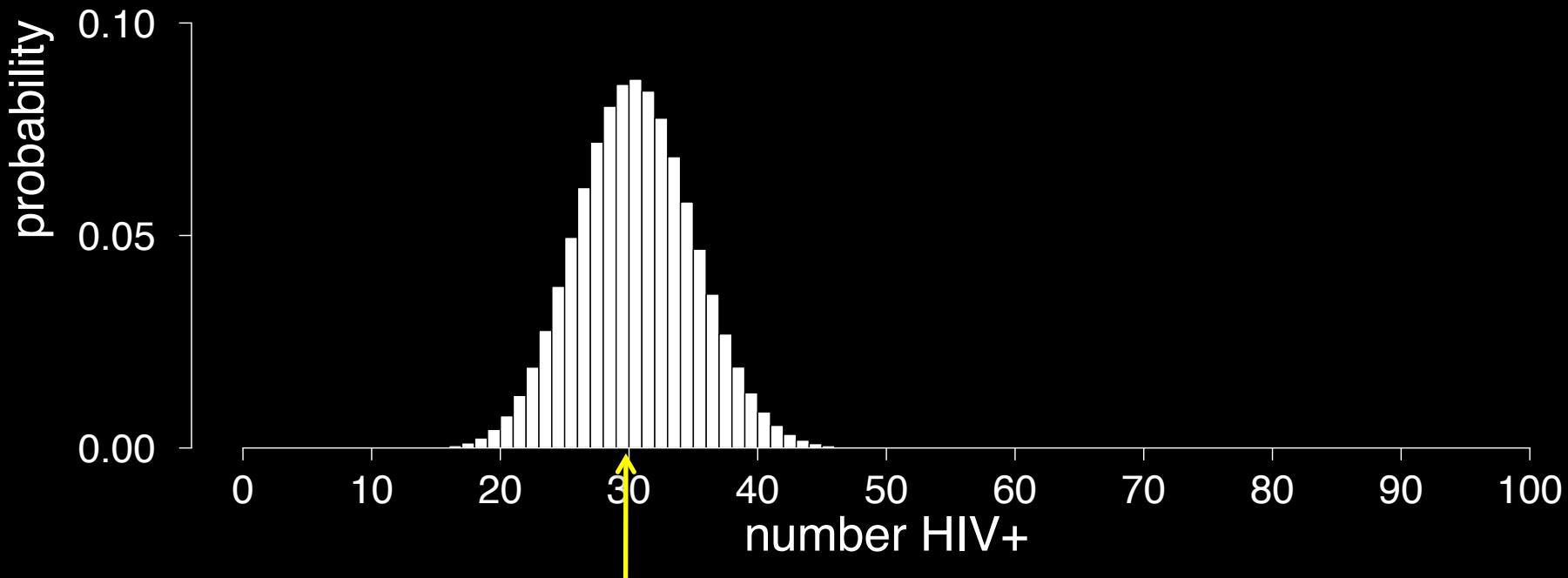
$$f(x) = \binom{100}{x} (0.3)^x (0.7)^{100-x}$$



```
barplot(dbinom(x = 0:100, size = 100, prob = .3), names.arg = 0:size)
```

In a population of 1,000,000 people with a true prevalence of 30%, the probability distribution of number of positive individuals if 100 are sampled:

$$f(x) = \binom{100}{x} (0.3)^x (0.7)^{100-x}$$



We sample 100 people once and 28 are positive:

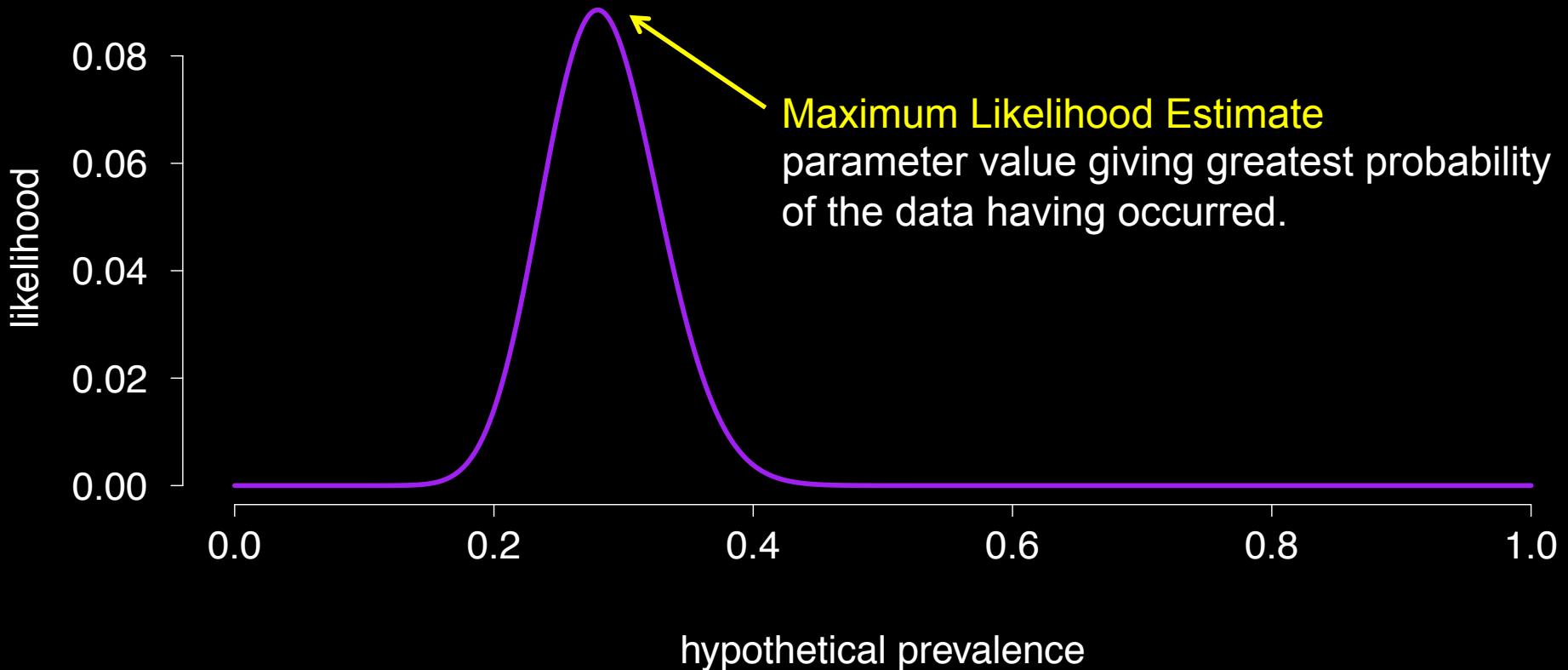
```
> rbinom(n = 1, size = 100, prob = .3)  
[1] 28
```

Defining Likelihood

- $L(\text{parameter} \mid \text{data}) = p(\text{data} \mid \text{parameter})$
 - Not a probability distribution.
 - Probabilities taken from many different distributions.
- function of x
- \downarrow
- PDF: $f(x|p) = \binom{n}{x} (p)^x (1-p)^{n-x}$
- LIKELIHOOD: $L(p|x) = \binom{n}{x} (p)^x (1-p)^{n-x}$
- ↑
- function of p

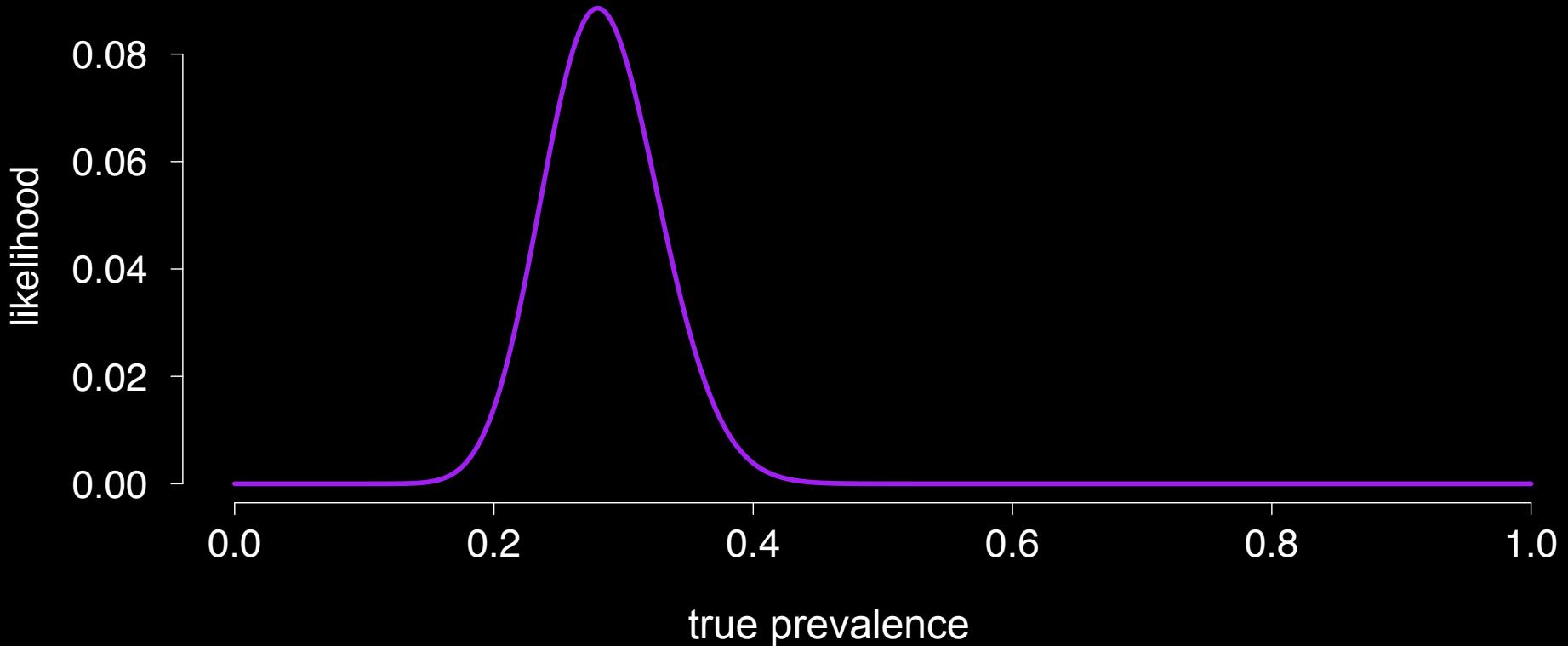
Frequentist ML: Estimate the MLE and 95% confidence bounds.

$$P(x = 28, n = 100 \mid \theta)$$



Bayesian Inference: Calculate the posterior probability distribution of every possible parameter value

$$P(x = 28, n = 100 | \theta)$$



$$P(\theta | x = 28, n = 100)$$

MCMC

What is the posterior probability distribution for the prevalence θ

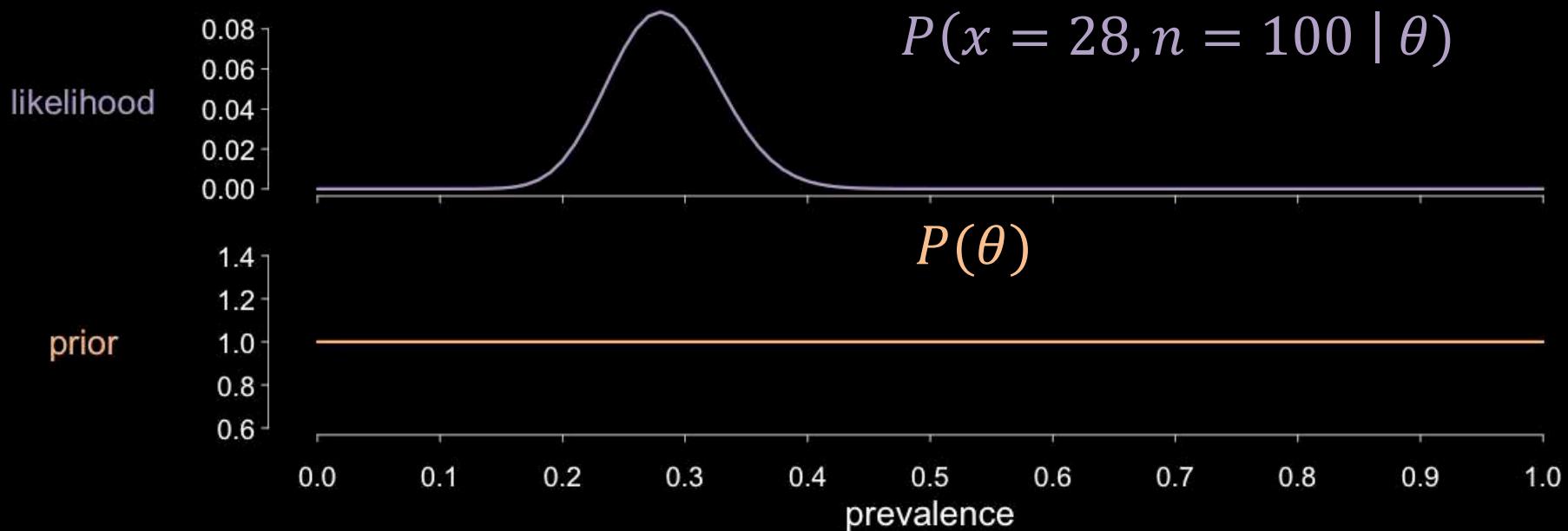
- when we observe 28/100 positive
- & if we have no prior beliefs about plausible prevalence

$$P(\theta | x = 28, n = 100) \propto P(x = 28, n = 100 | \theta) P(\theta)$$

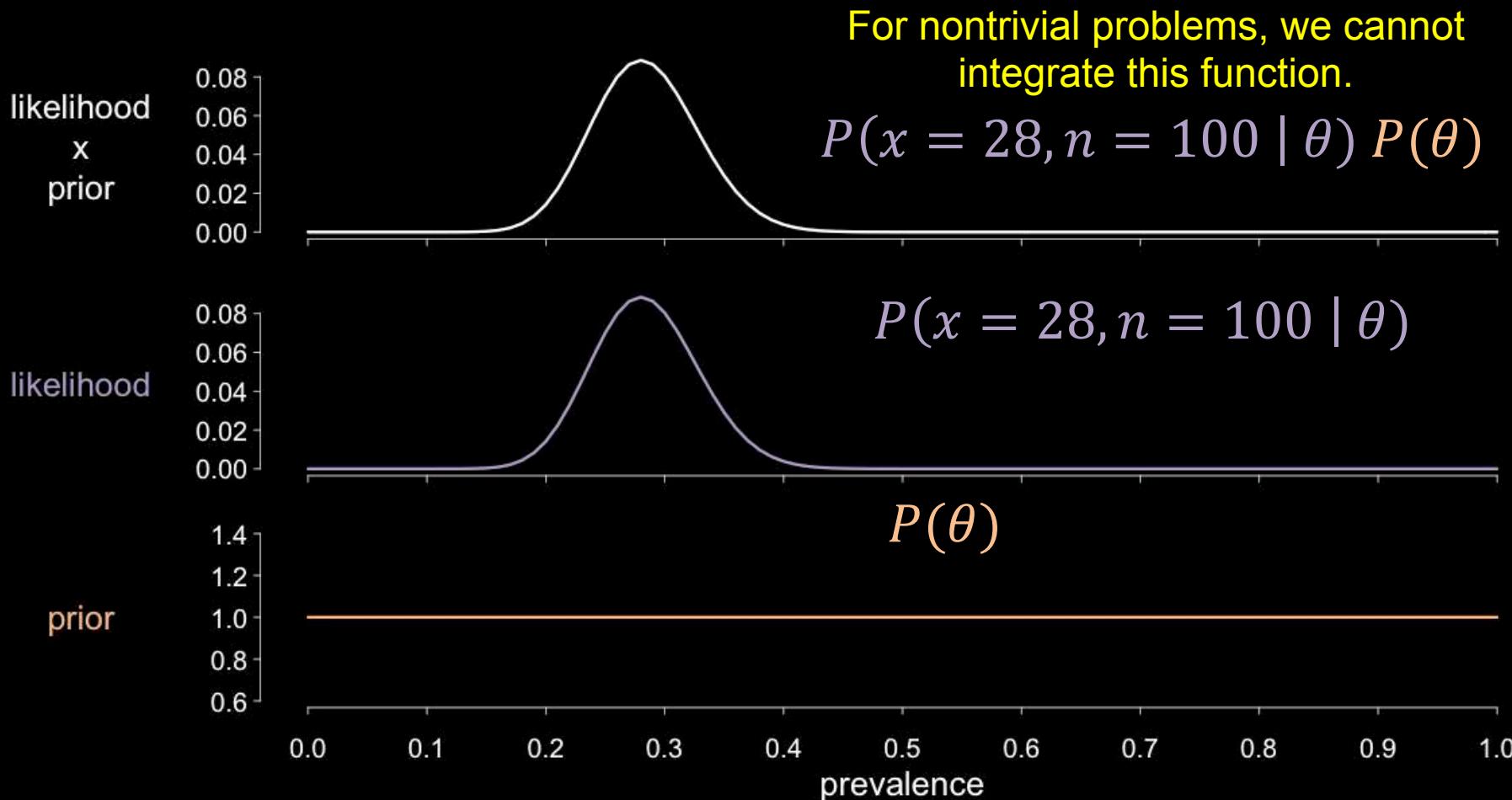
$$\int P(\theta | x = 28, n = 100) d\theta = 1$$

Let's use the Metropolis-Hastings MCMC algorithm to estimate

$$P(\theta | x = 28, n = 100)$$



$$P(\theta \mid x = 28, n = 100) = \frac{P(x = 28, n = 100 \mid \theta) P(\theta)}{\int P(x = 28, n = 100 \mid \theta) P(\theta) d\theta}$$



MCMC sample distribution

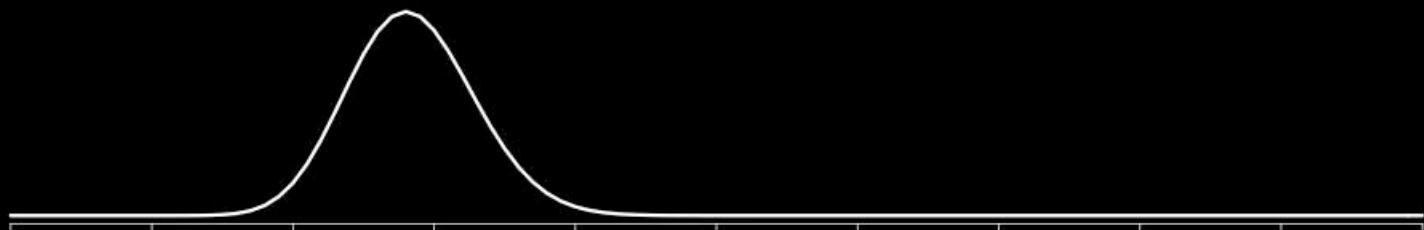
median

MCMC is an algorithm that creates a sample from the posterior.

95% credible intervals

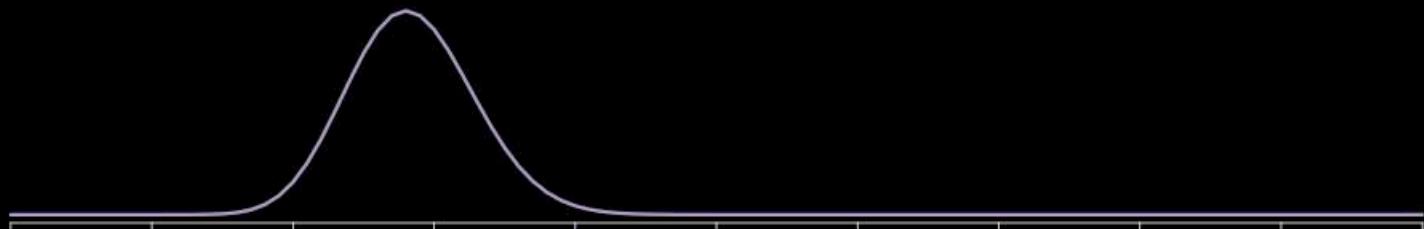
likelihood
x prior

0.08
0.06
0.04
0.02
0.00



likelihood

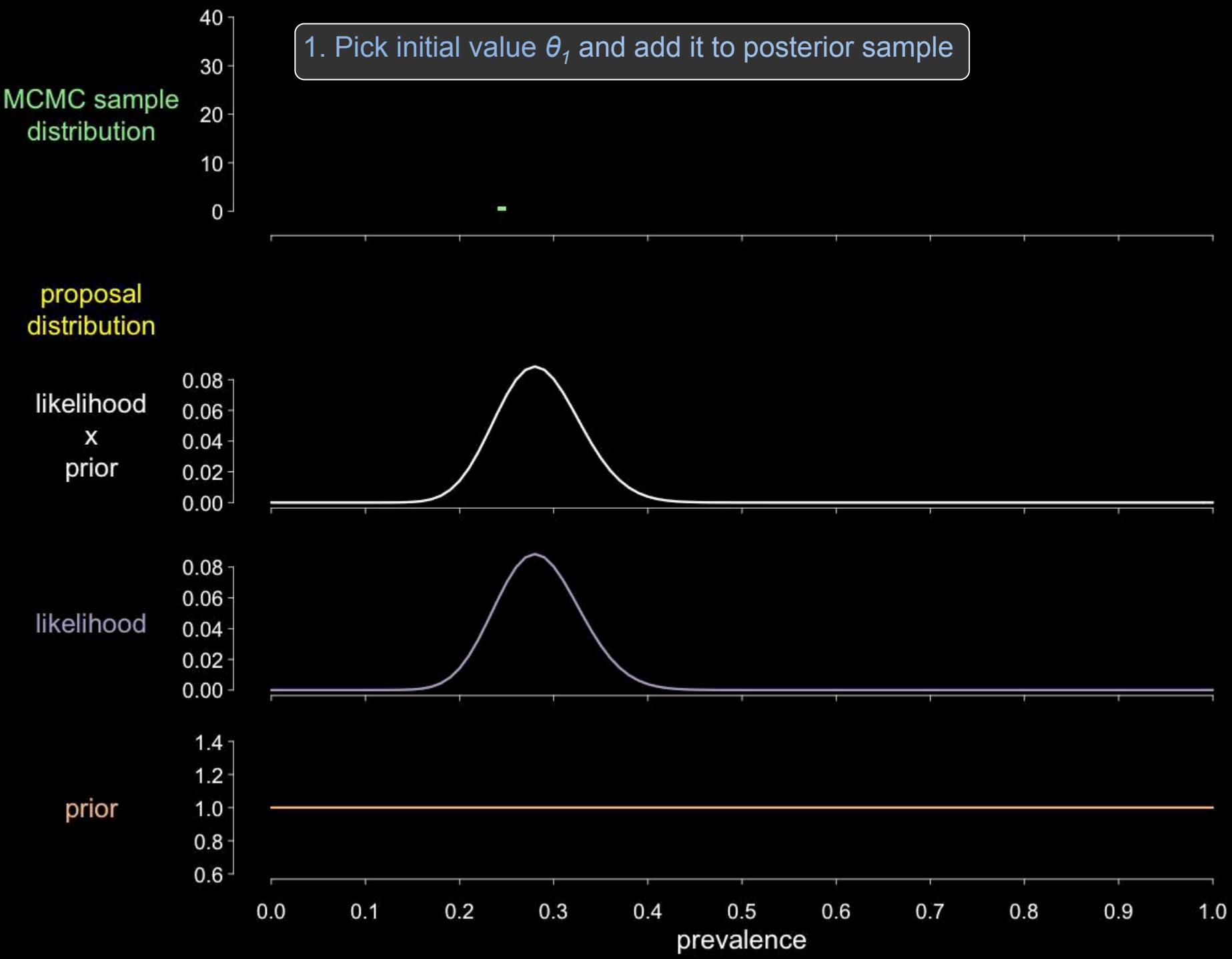
0.08
0.06
0.04
0.02
0.00



prior

1.4
1.2
1.0
0.8
0.6





MCMC sample distribution

2. Sample θ_{proposal} from proposal distribution around current value

proposal distribution

likelihood
x prior

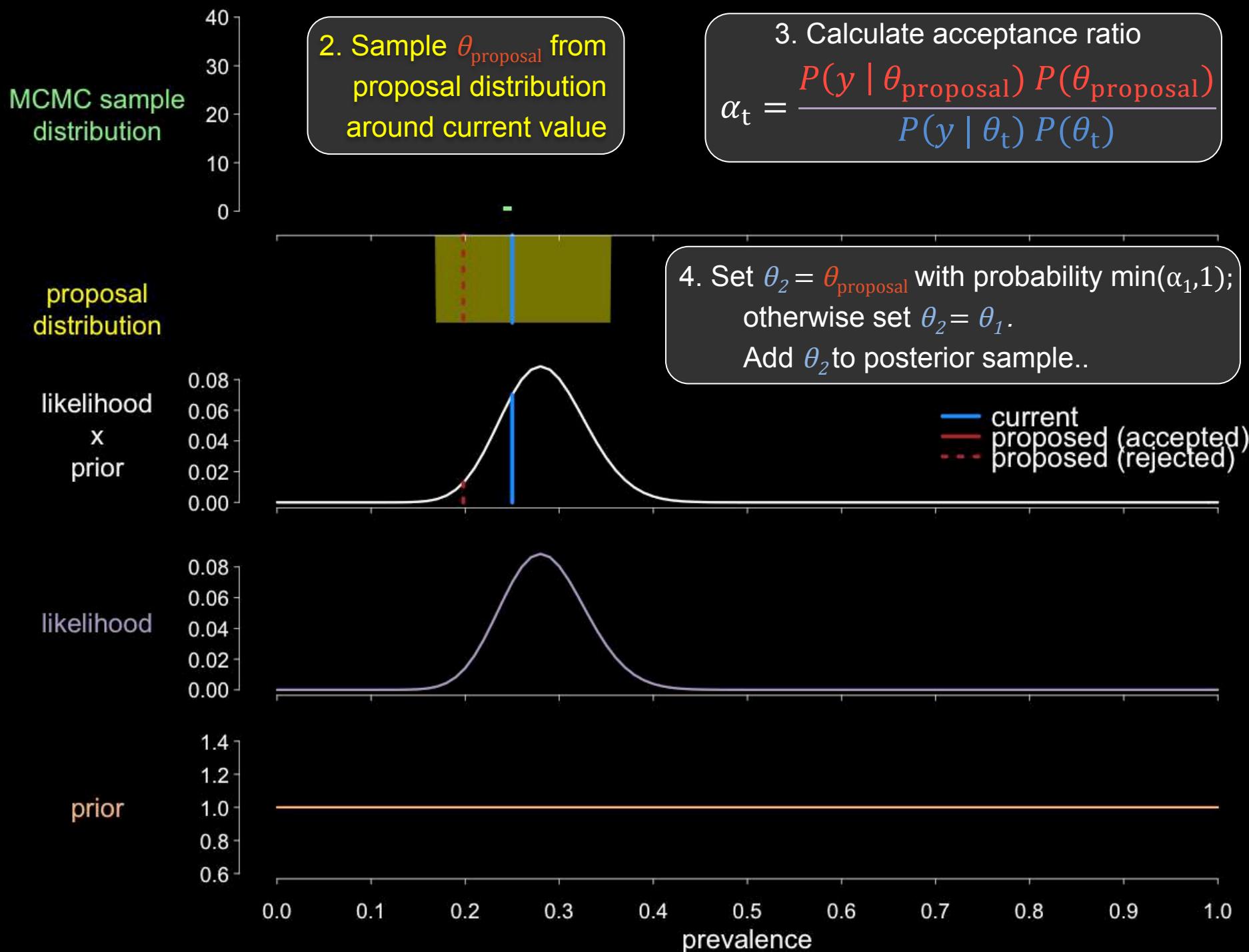
— current

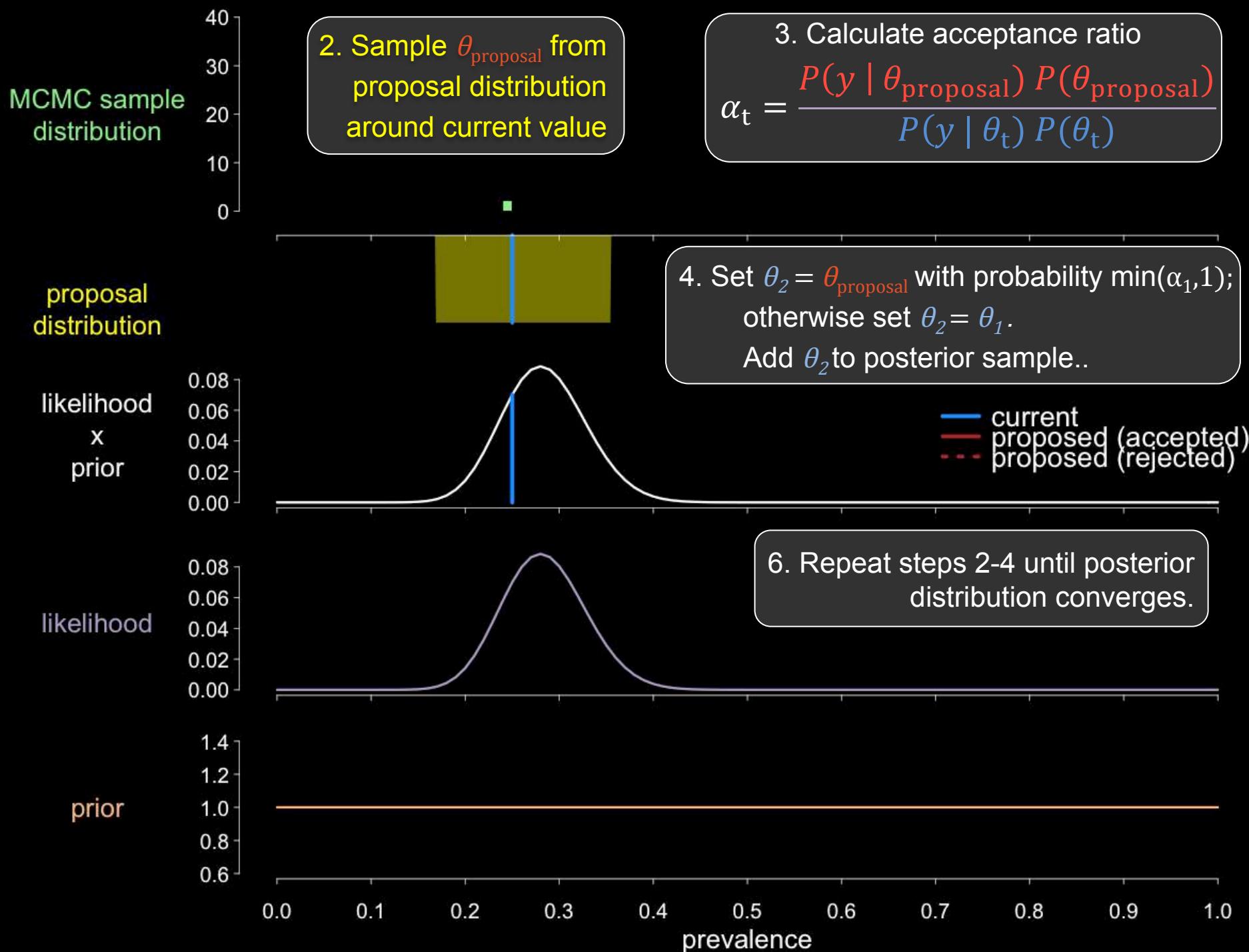
likelihood

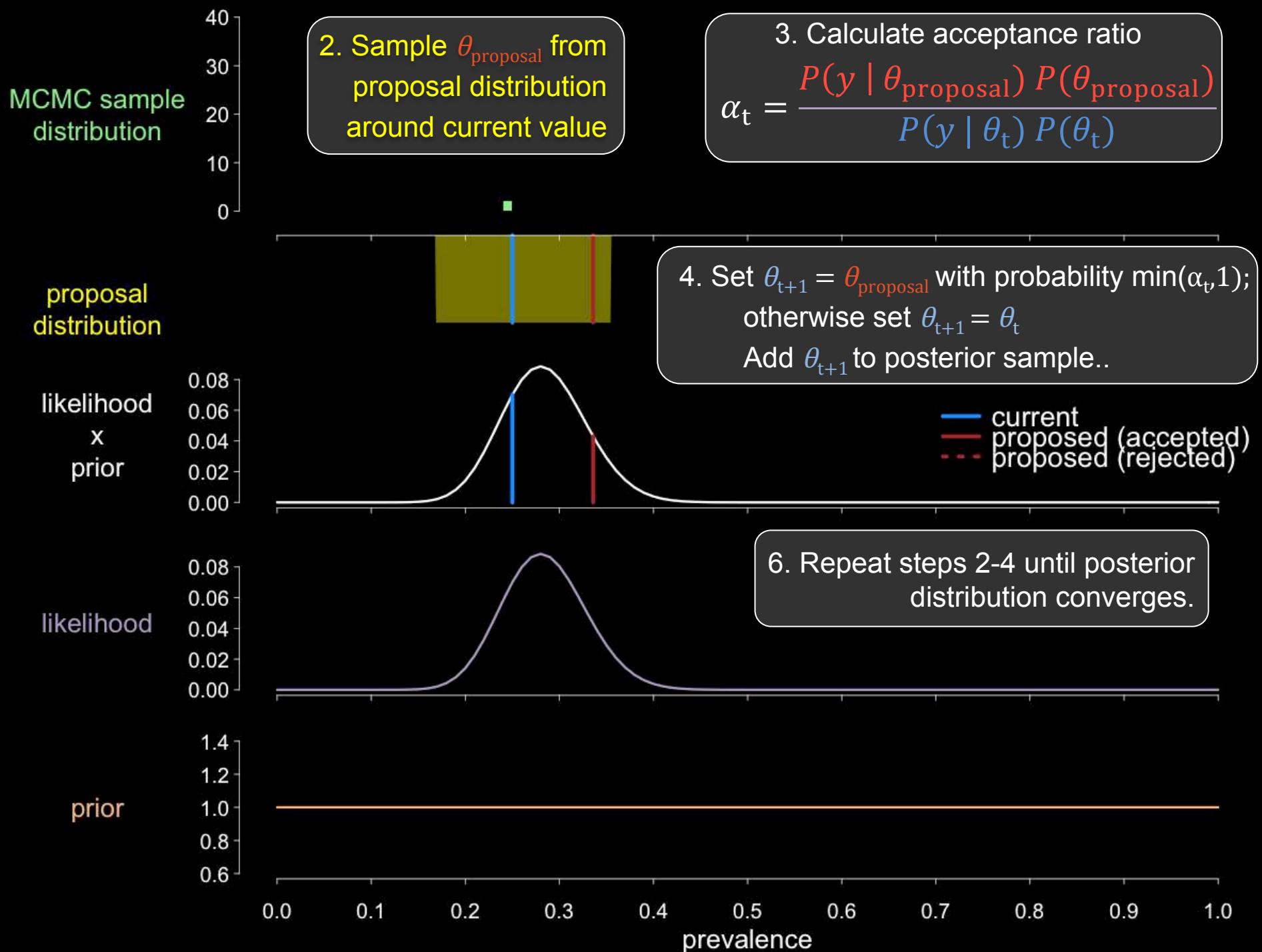
prior

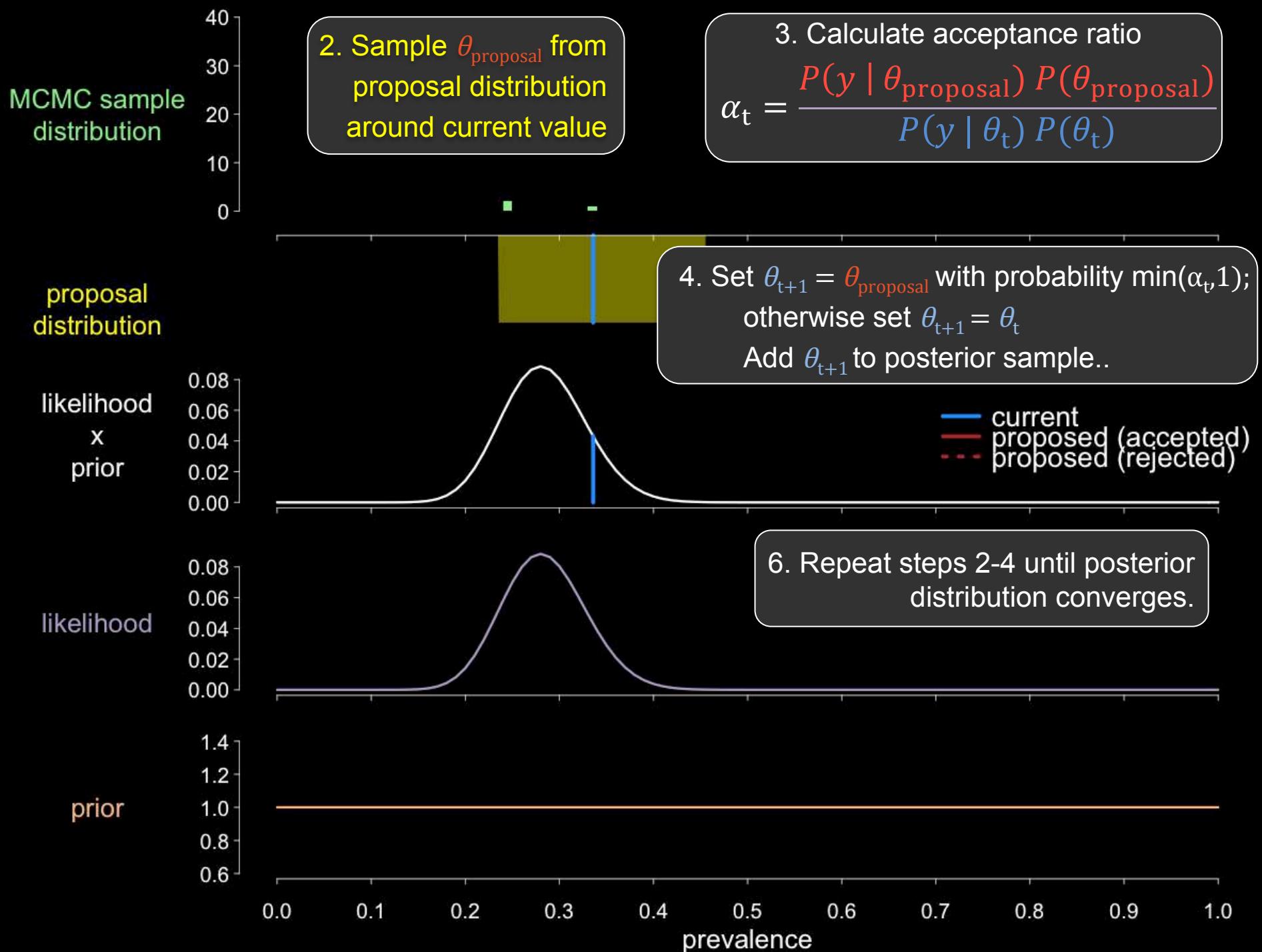
0.0 0.1 0.2 0.3 0.4 0.5 0.6 0.7 0.8 0.9 1.0

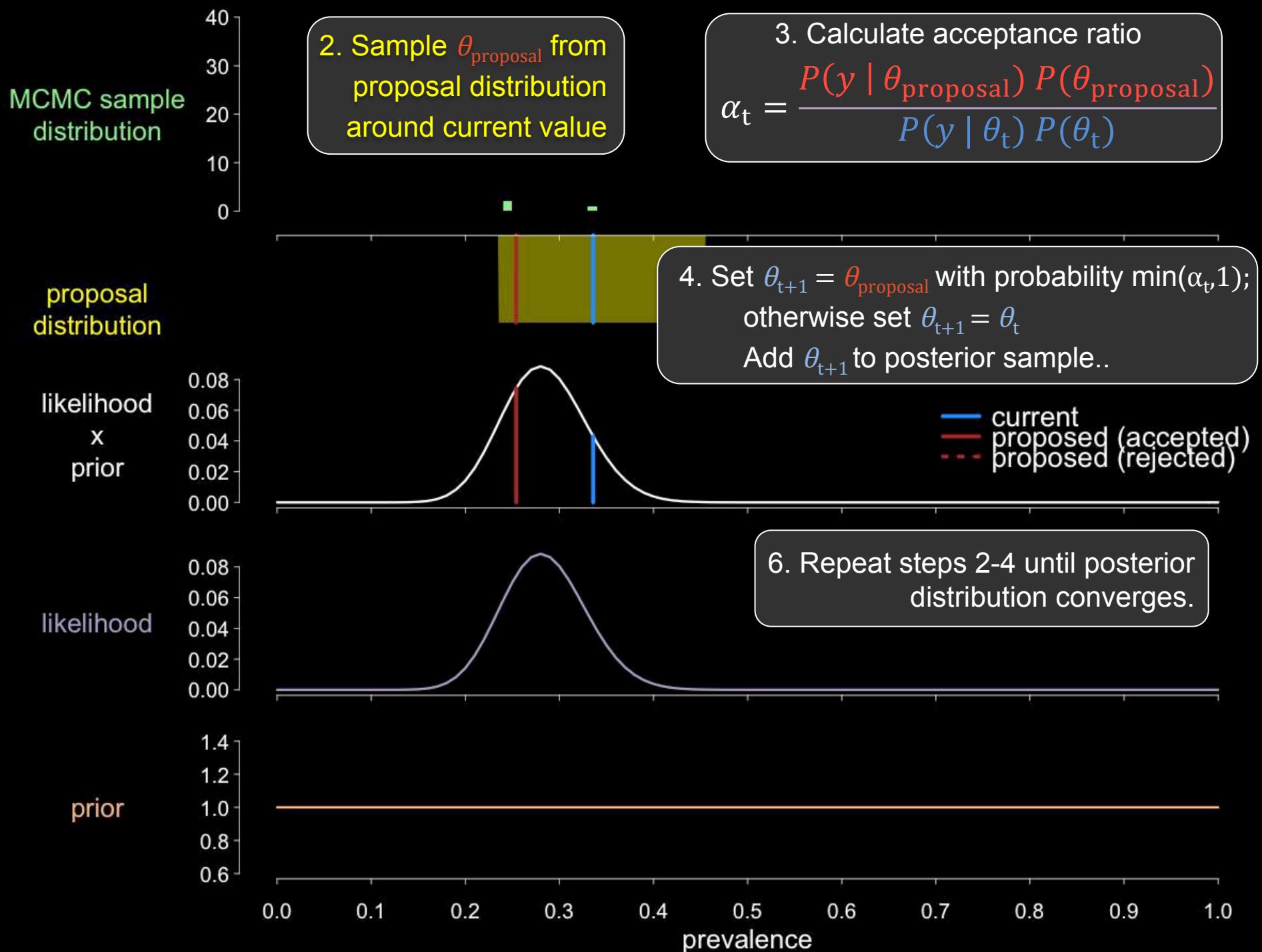
prevalence

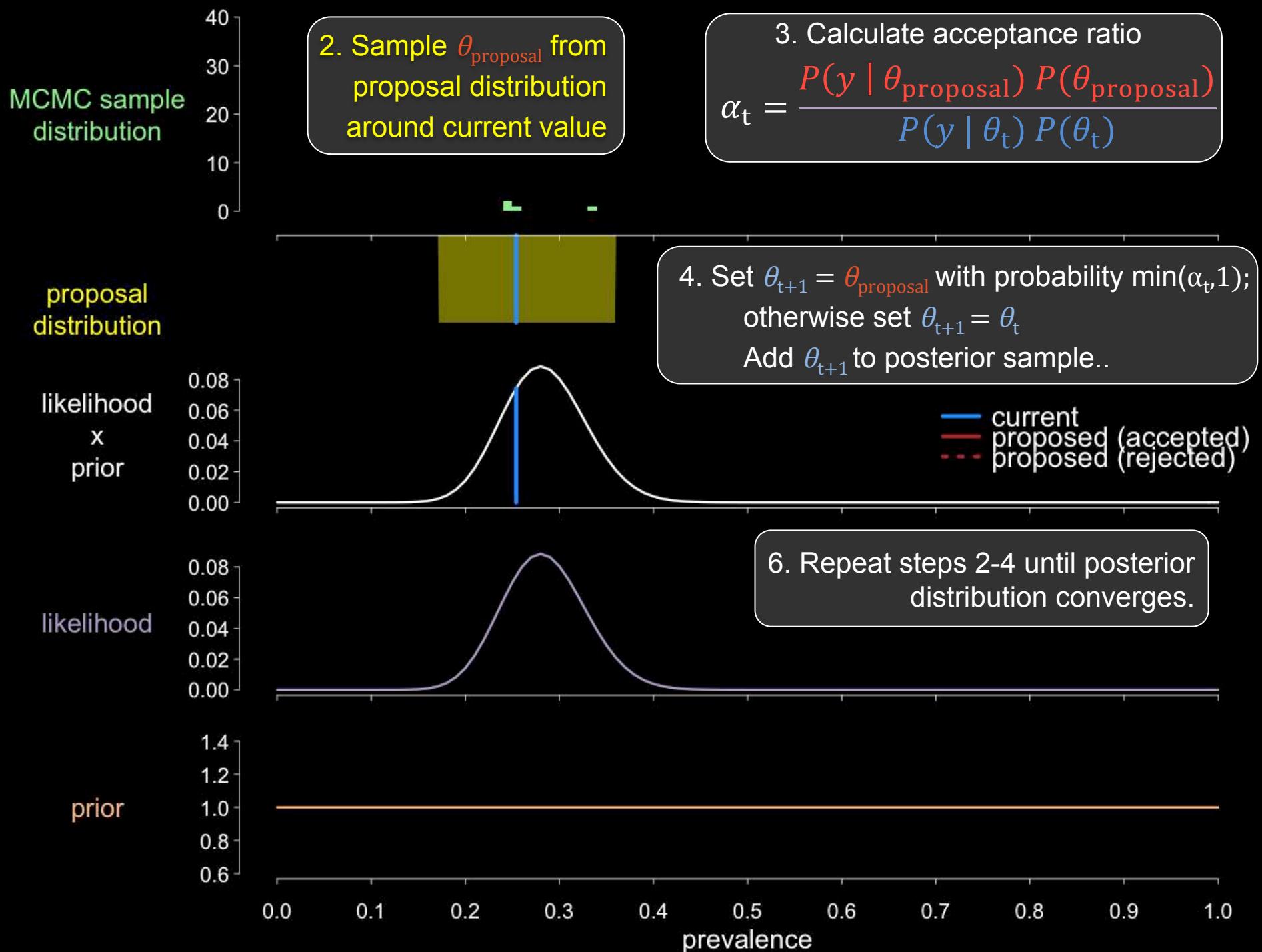






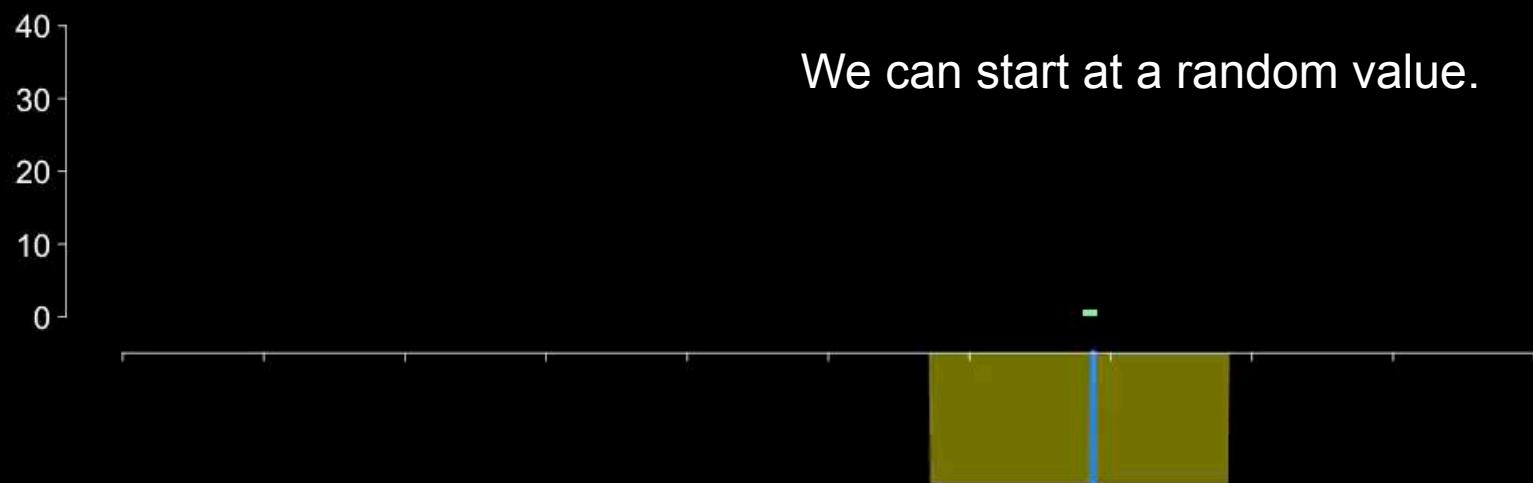






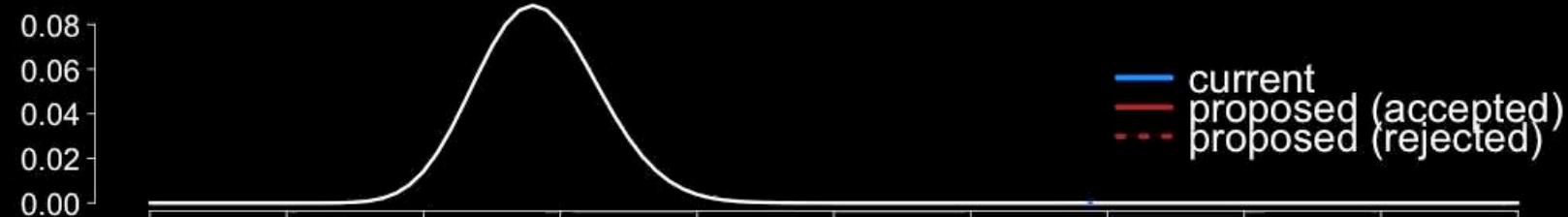
We can start at a random value.

MCMC sample
distribution



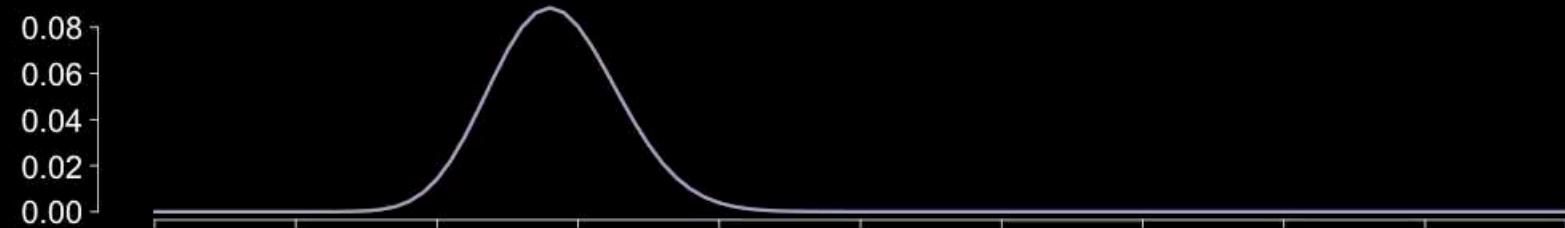
proposal
distribution

likelihood
x
prior

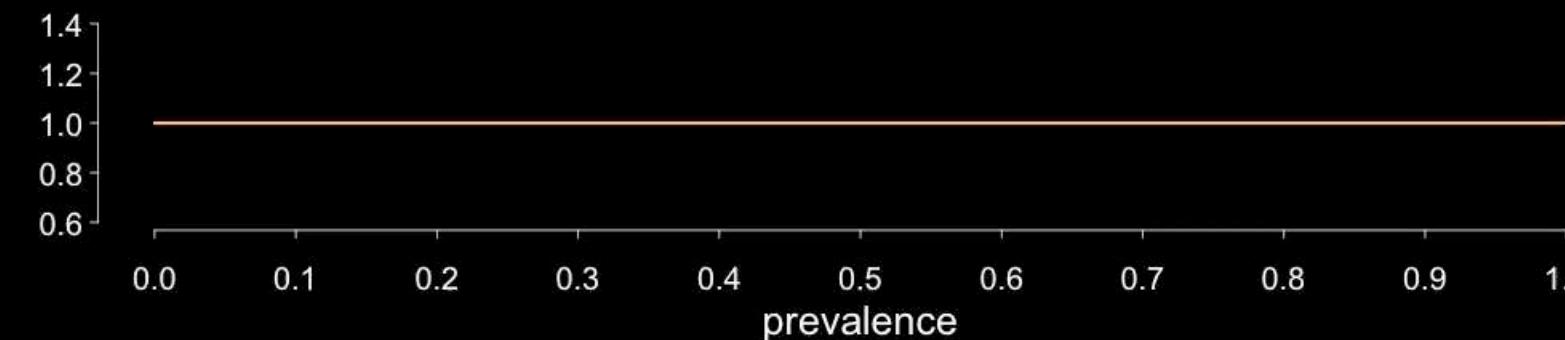


— current
— proposed (accepted)
- - - proposed (rejected)

likelihood



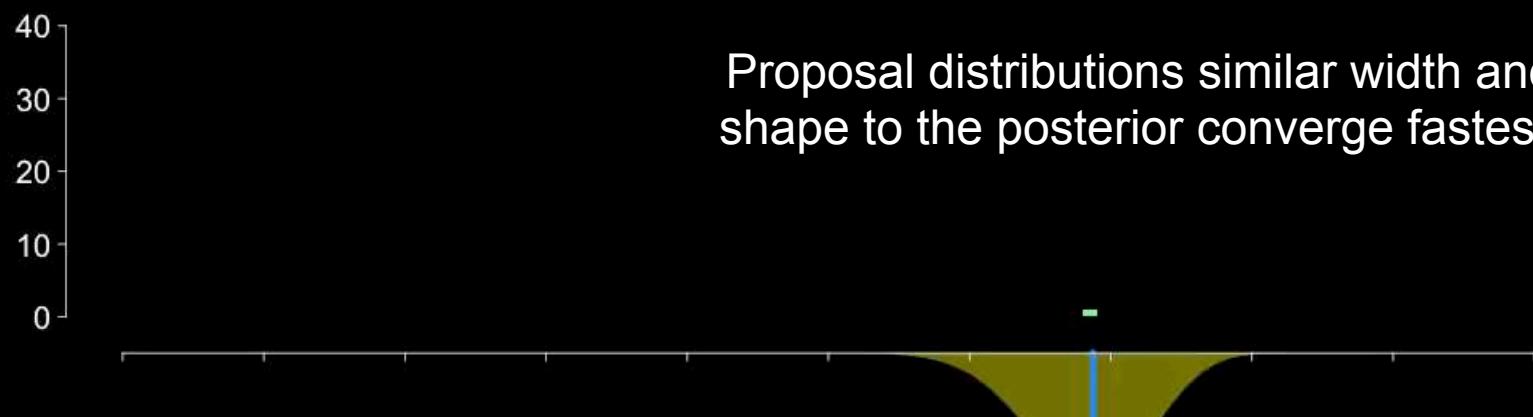
prior



prevalence

Proposal distributions similar width and shape to the posterior converge fastest.

MCMC sample distribution



proposal distribution

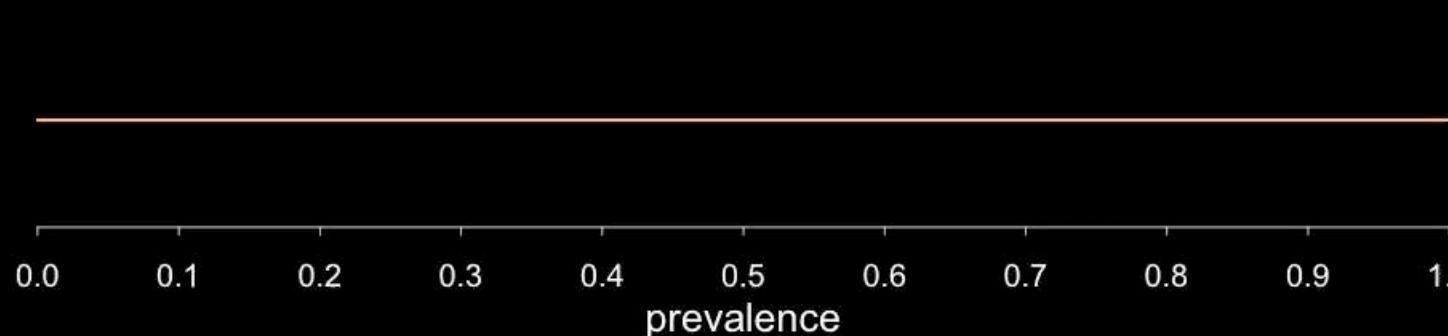
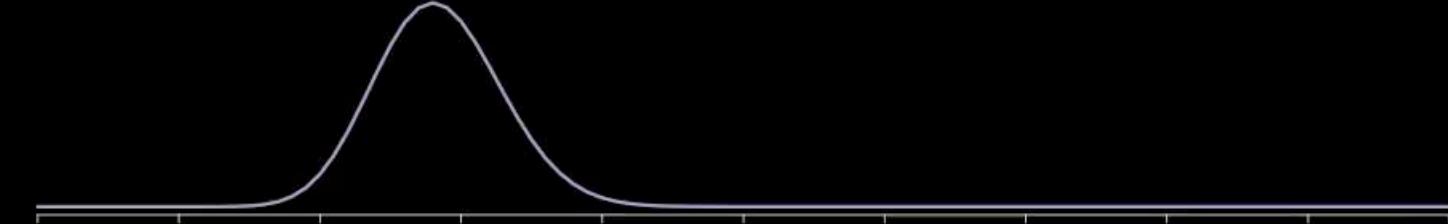
likelihood
x prior

Gaussian Proposal

— current
— proposed (accepted)
- - - proposed (rejected)

likelihood

prior



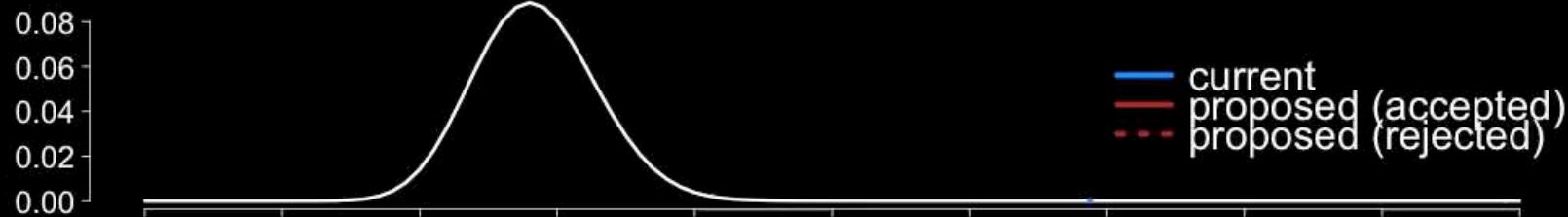
Wider proposal distributions make acceptance rare and slow down MCMC convergence.

MCMC sample distribution

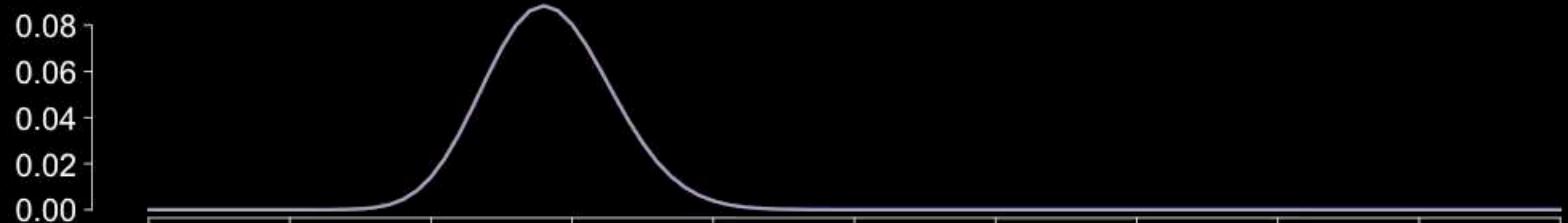


proposal distribution

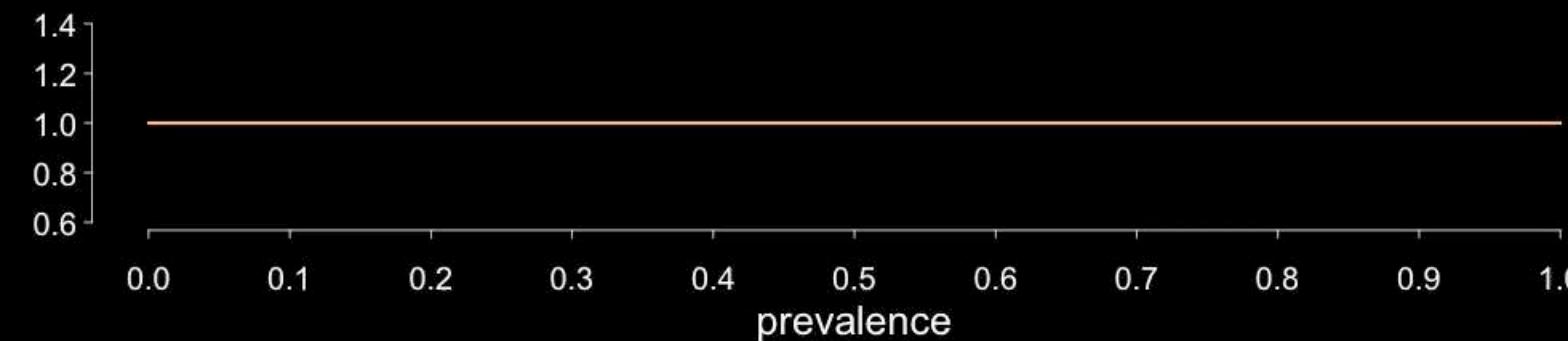
likelihood
x prior



likelihood



prior



Narrow proposal distributions make acceptance common but search slowly, and also slow down MCMC convergence.

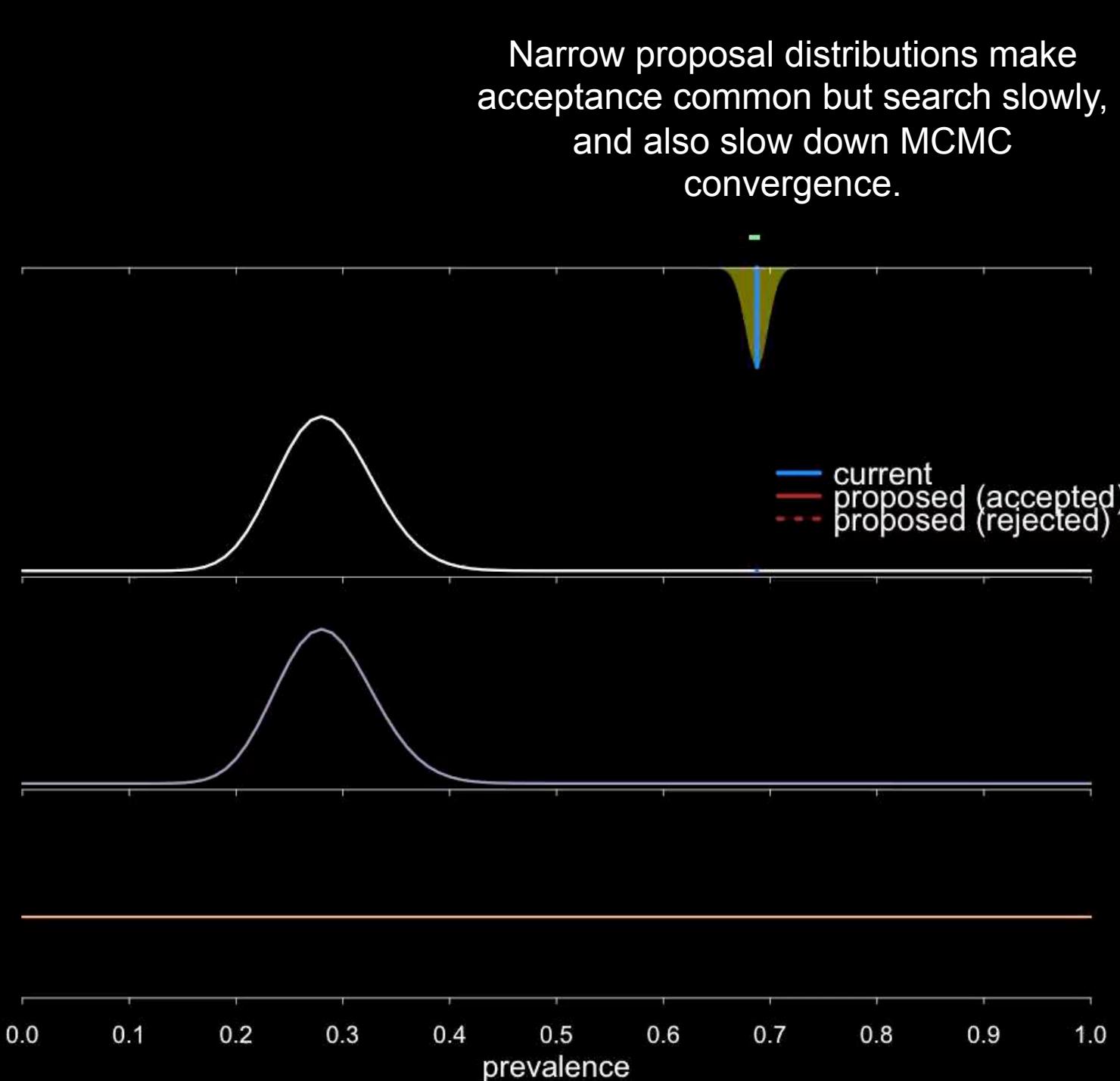
MCMC sample distribution

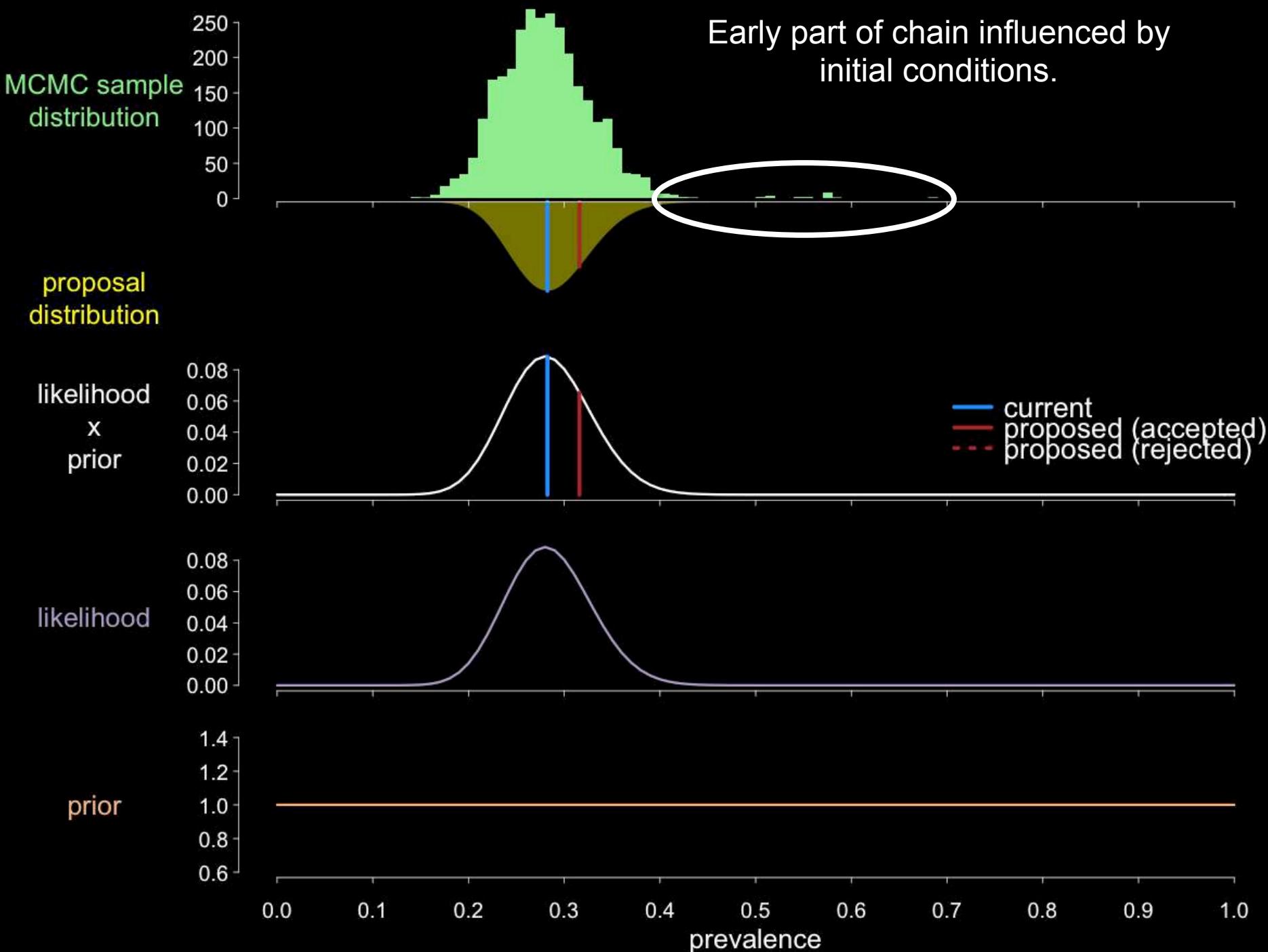
proposal distribution

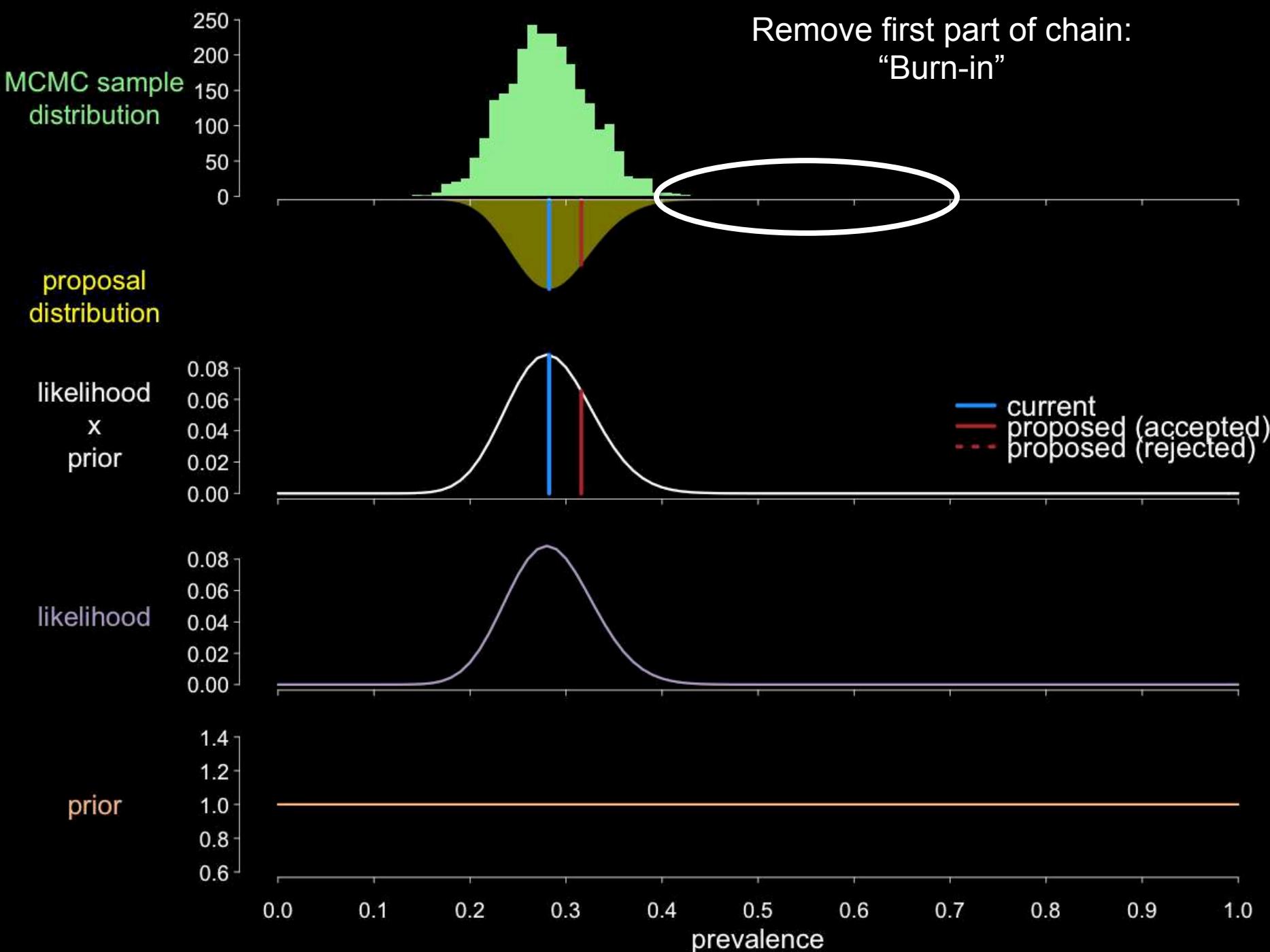
likelihood
x prior

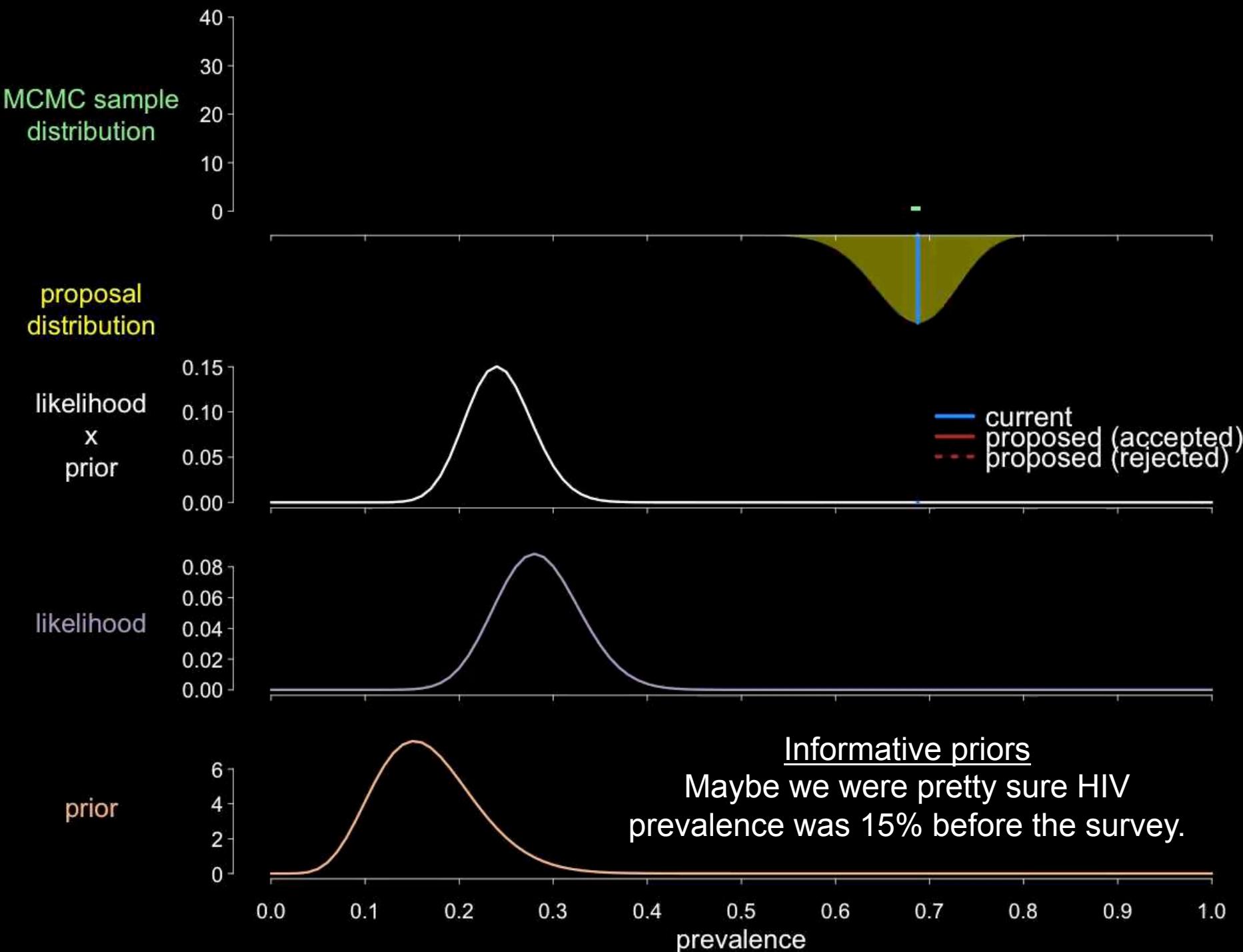
likelihood

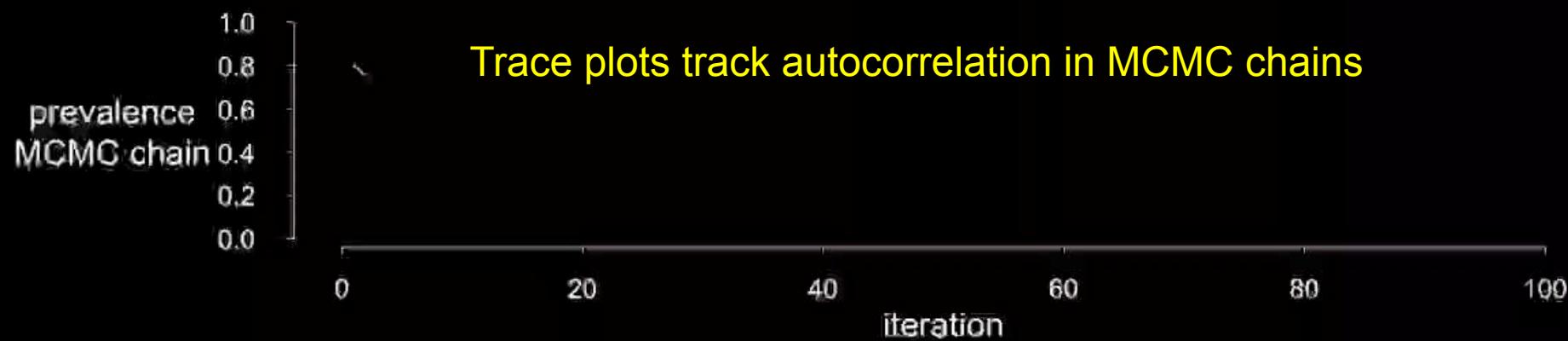
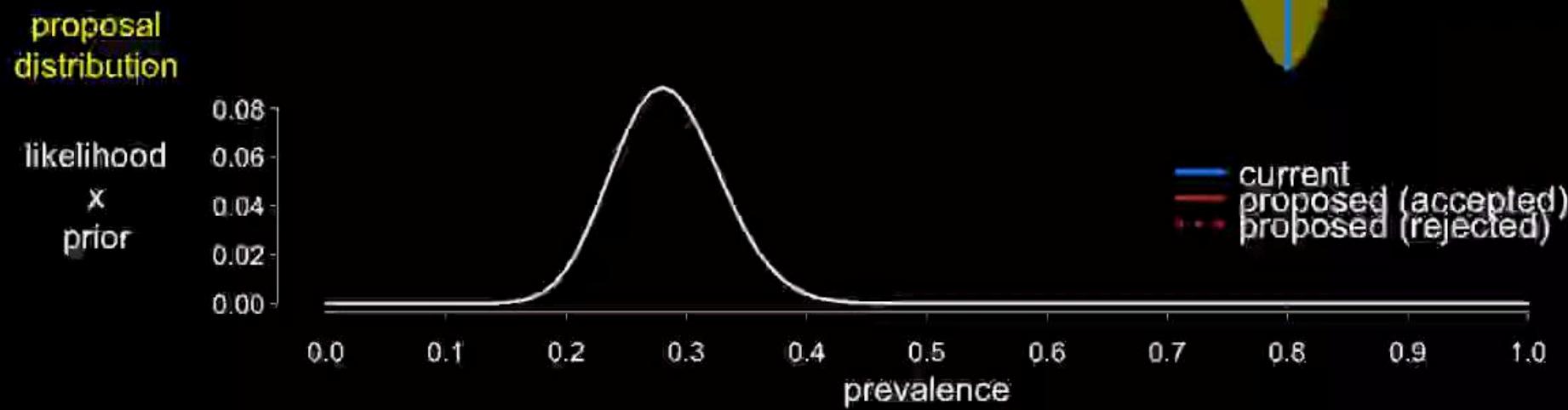
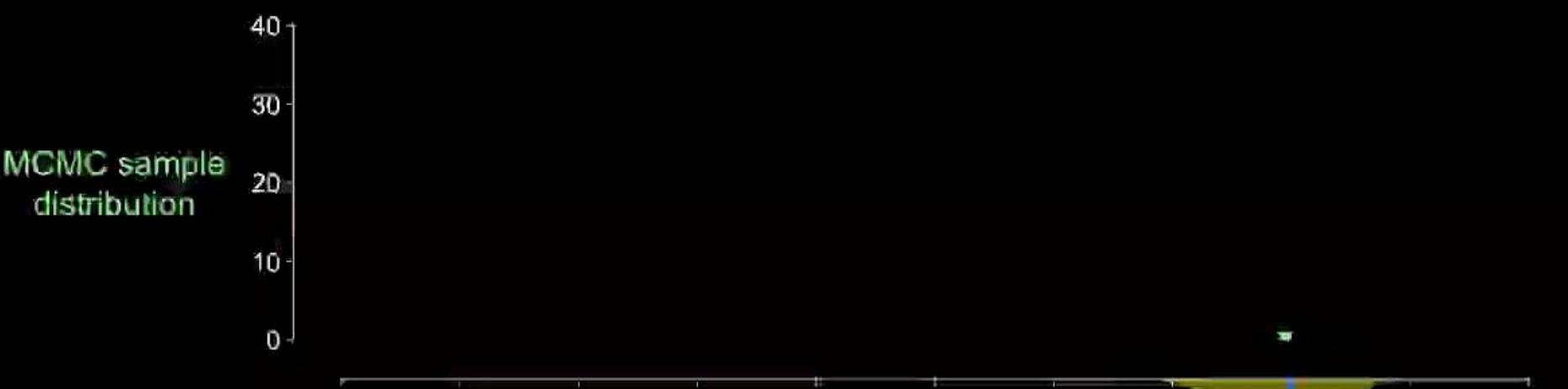
prior

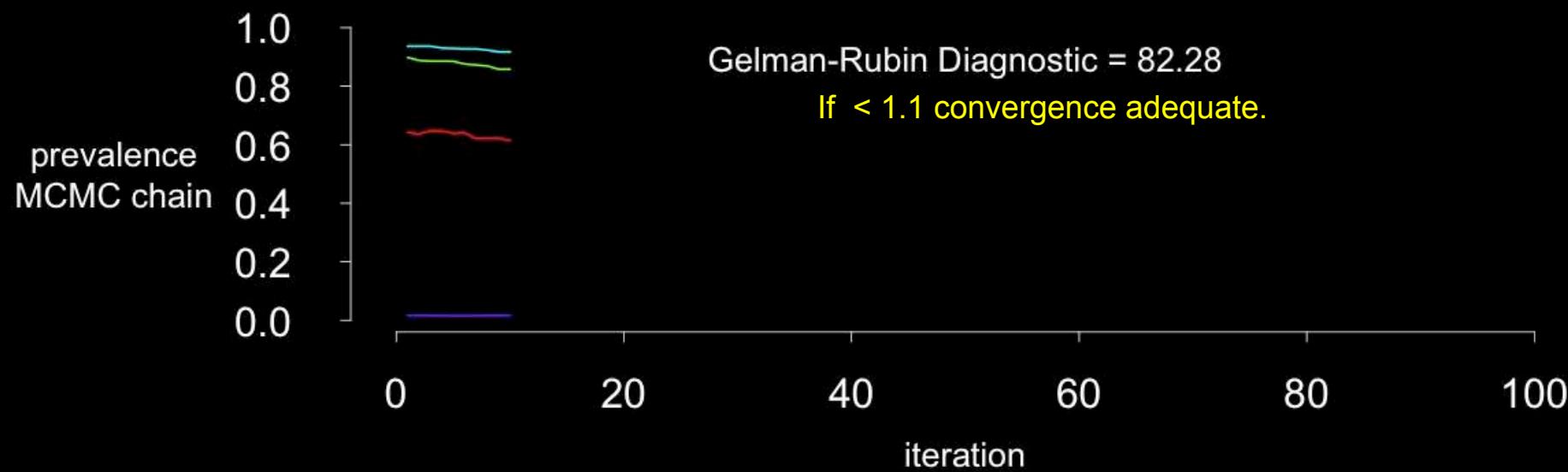
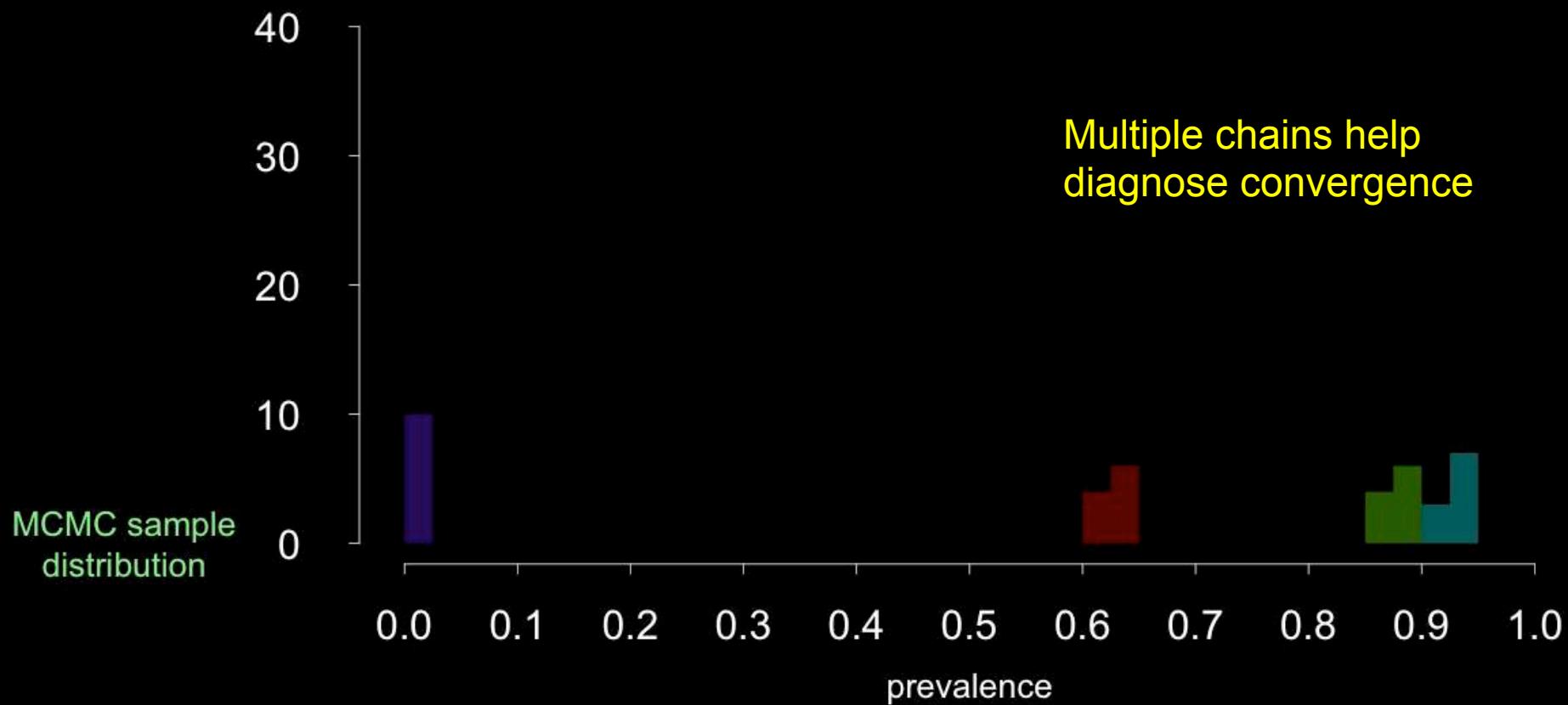












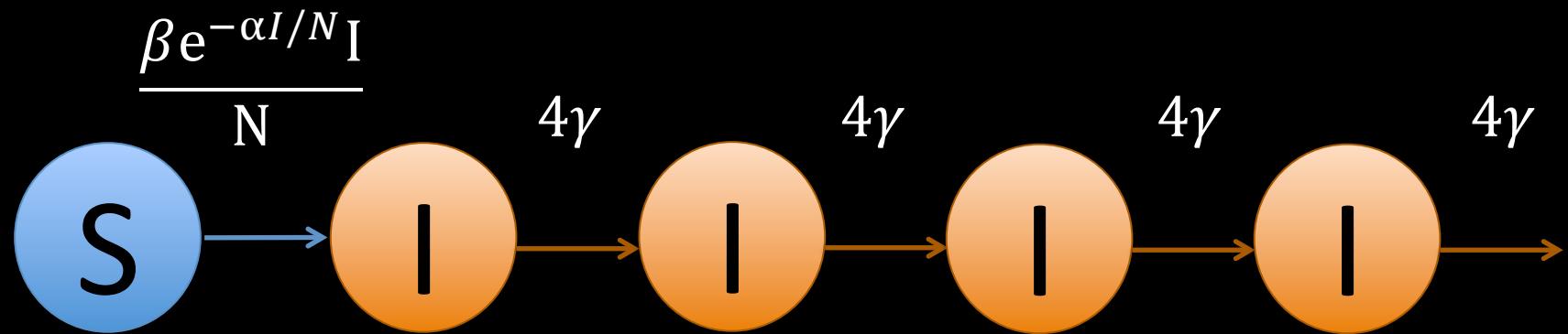
Defining MCMC

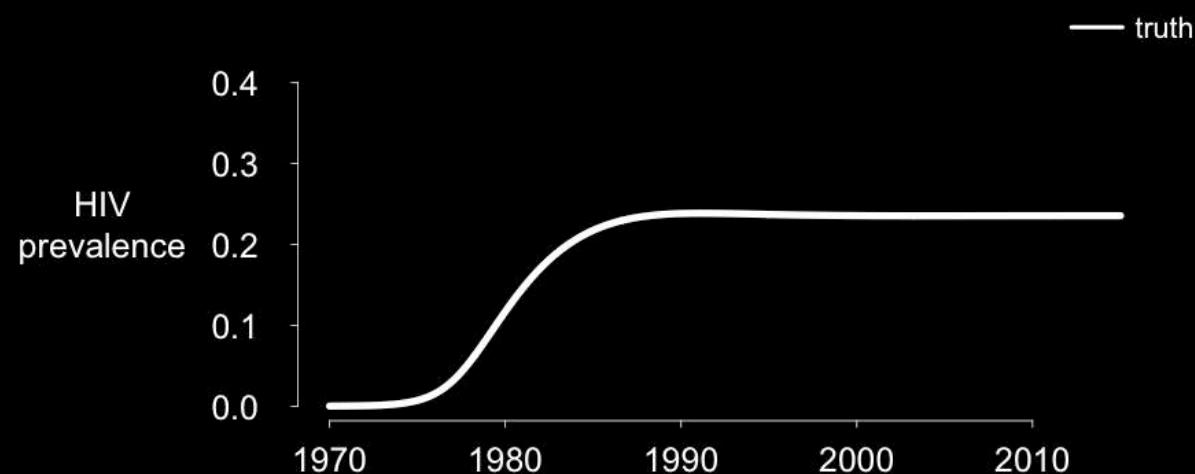
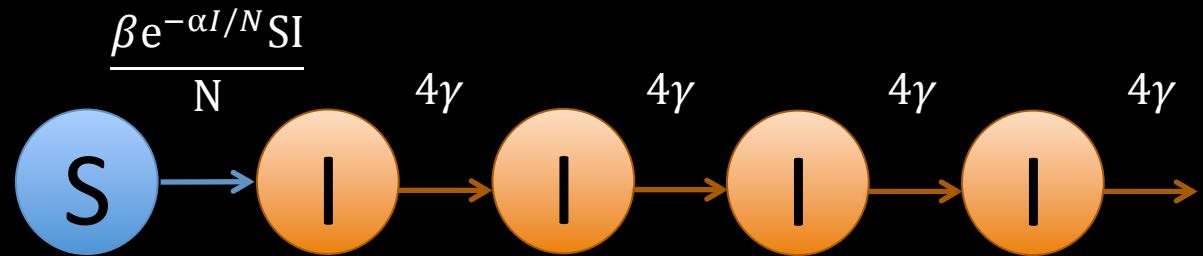
- Markov Chain = each state is a function of the last state
- Monte Carlo = stochastic Markov Chains
- MCMC = Markov Chains that eventually converge to a desired probability distribution.
- Samples are correlated!
- Convergence guaranteed, but only in long run.
- Convergence diagnostics are important

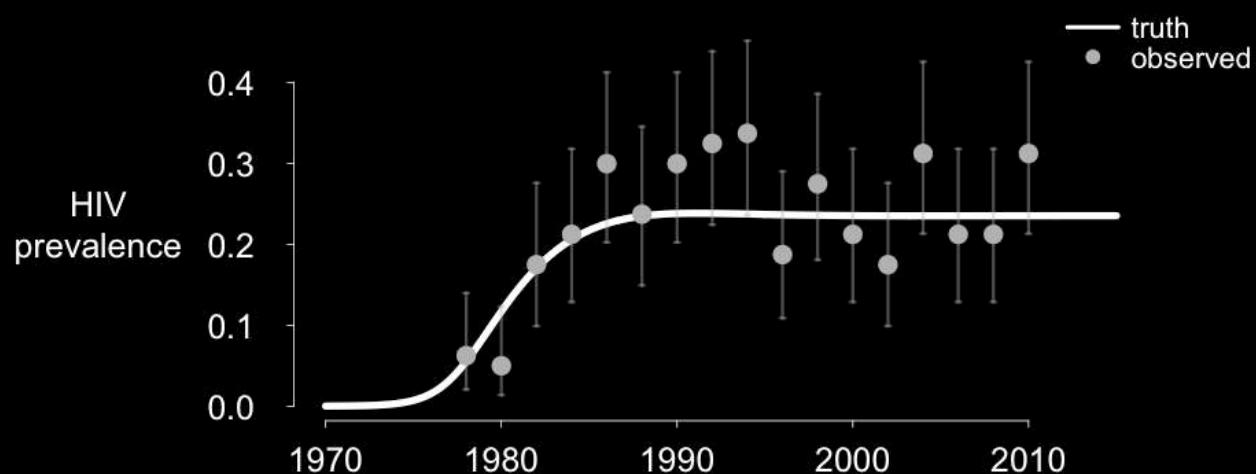
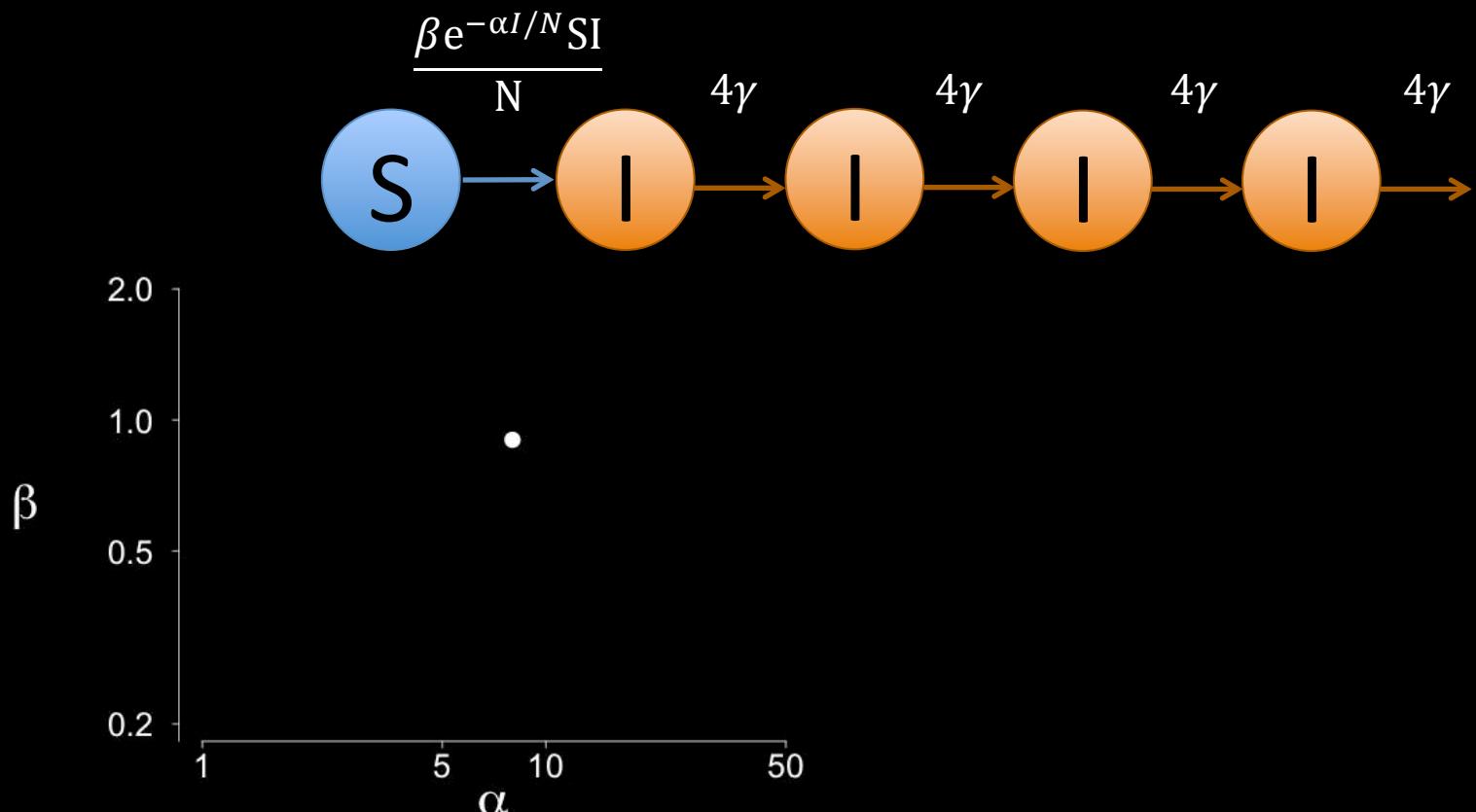
Multivariate MCMC

- Proposing parameters in N-dimensional space.
- Propose parameters one at a time (sequential sampling)

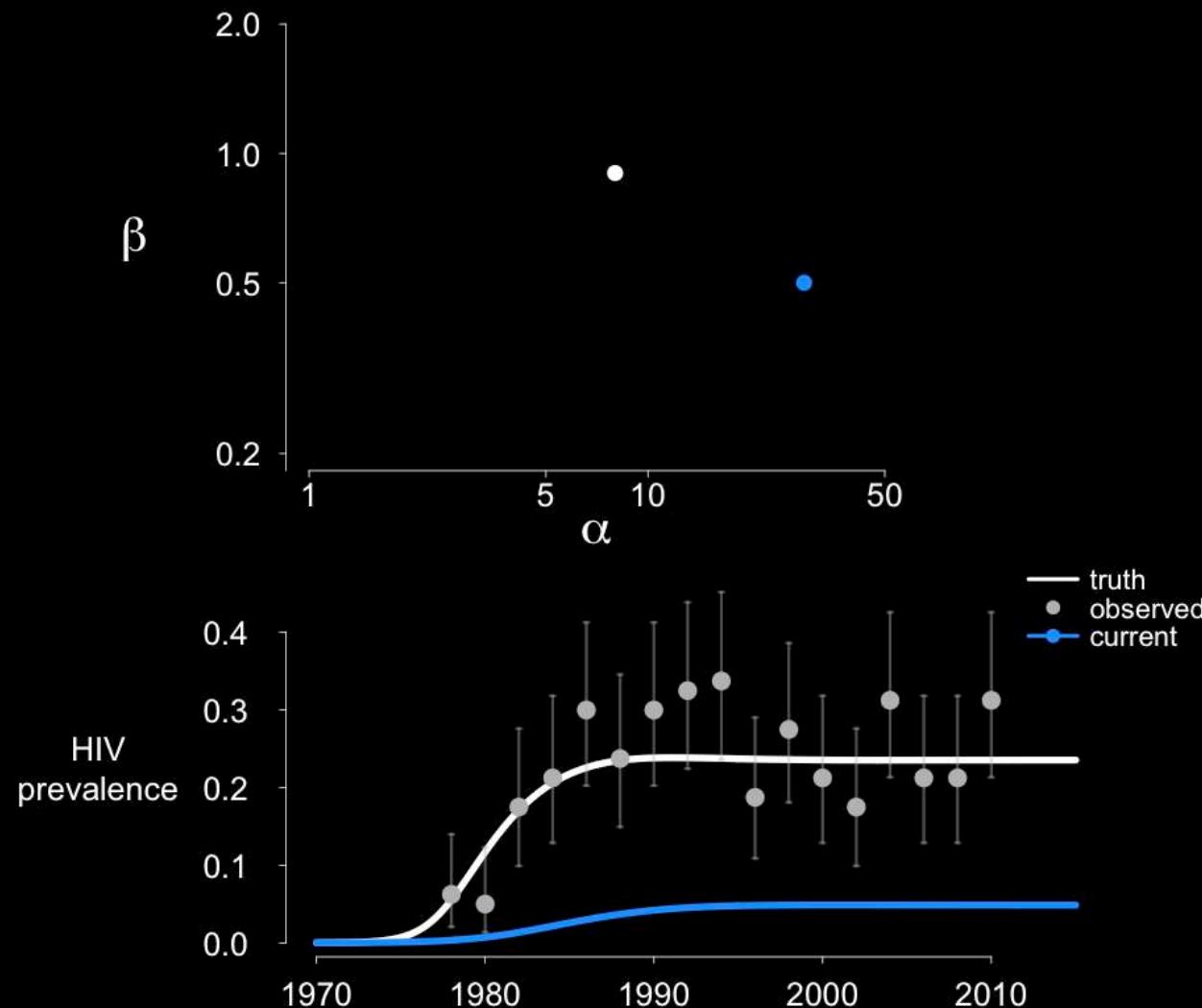
2-dimensional example



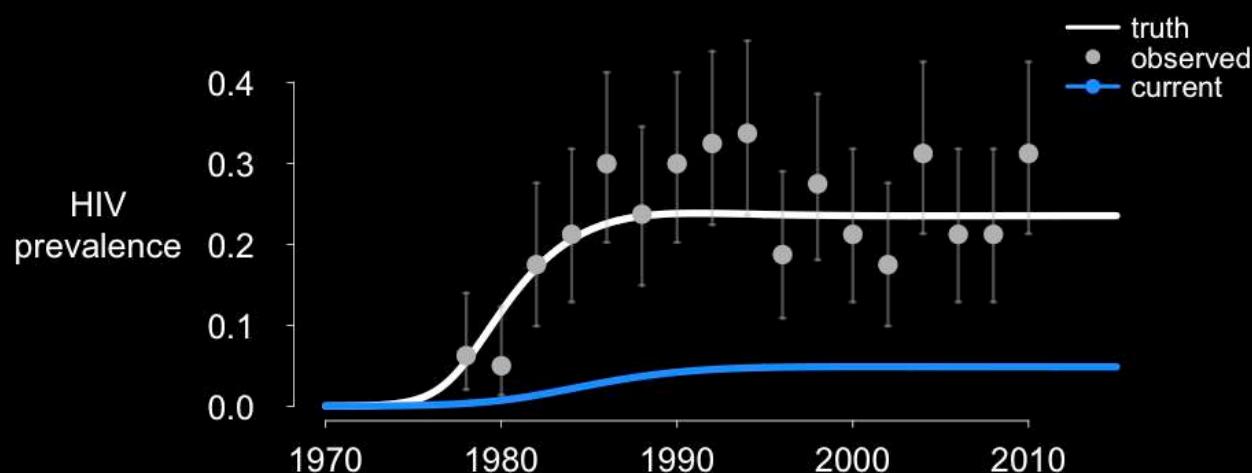
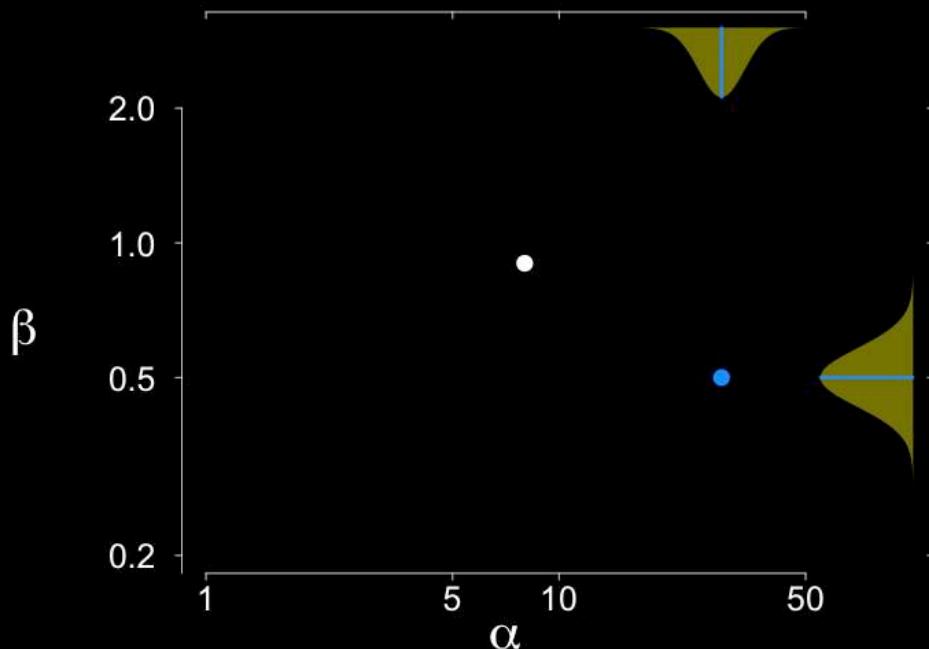




Start with an initial guess for both parameters.

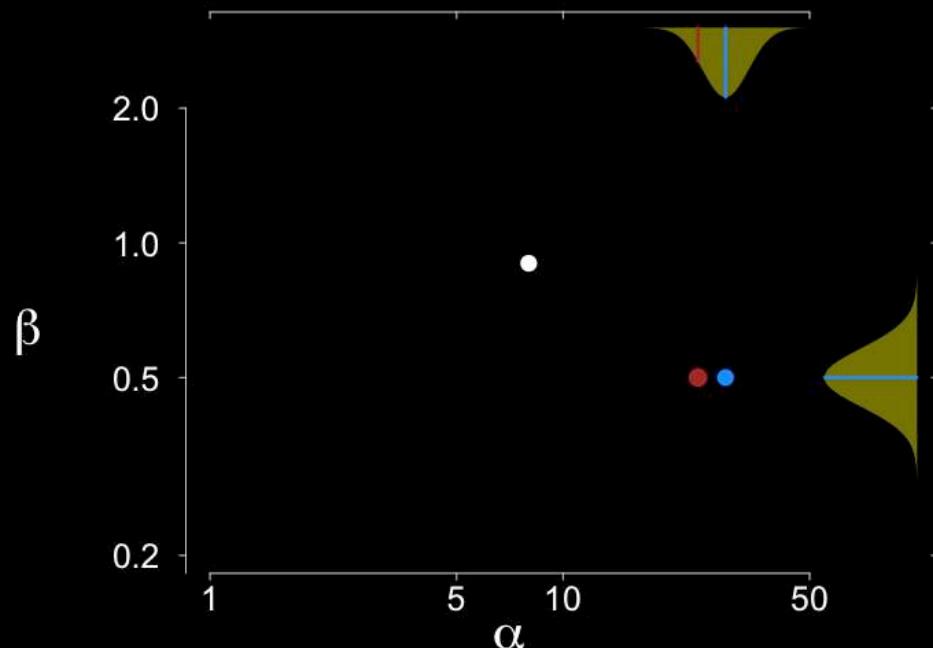


Choose proposal distributions for both parameters



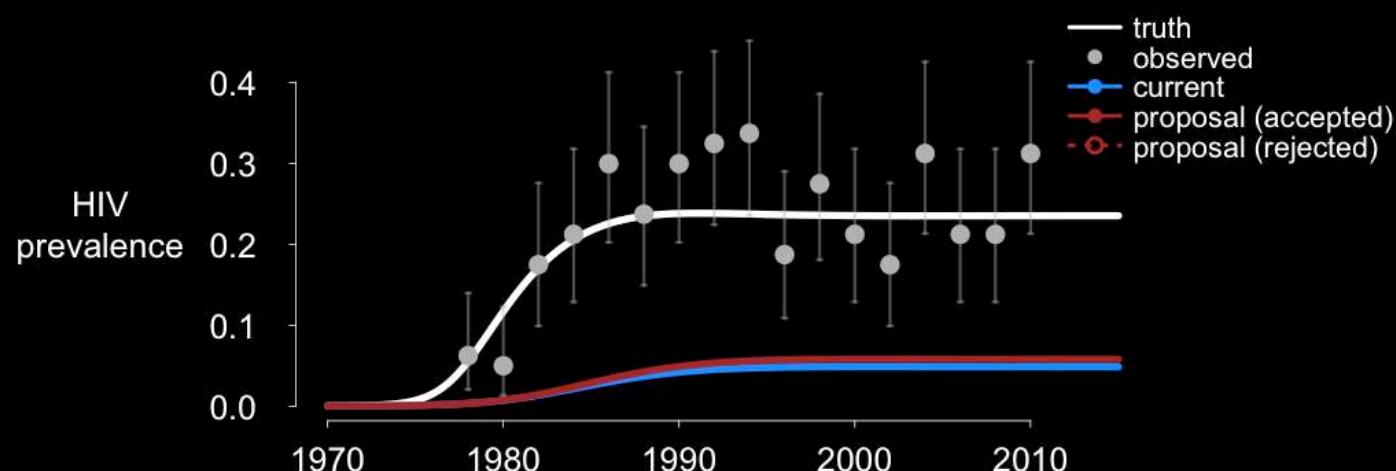
$$\alpha_t = \frac{P(y | \theta_{\text{proposal}}) P(\theta_{\text{proposal}})}{P(y | \theta_t) P(\theta_t)}$$

Propose new value for parameter at a time.

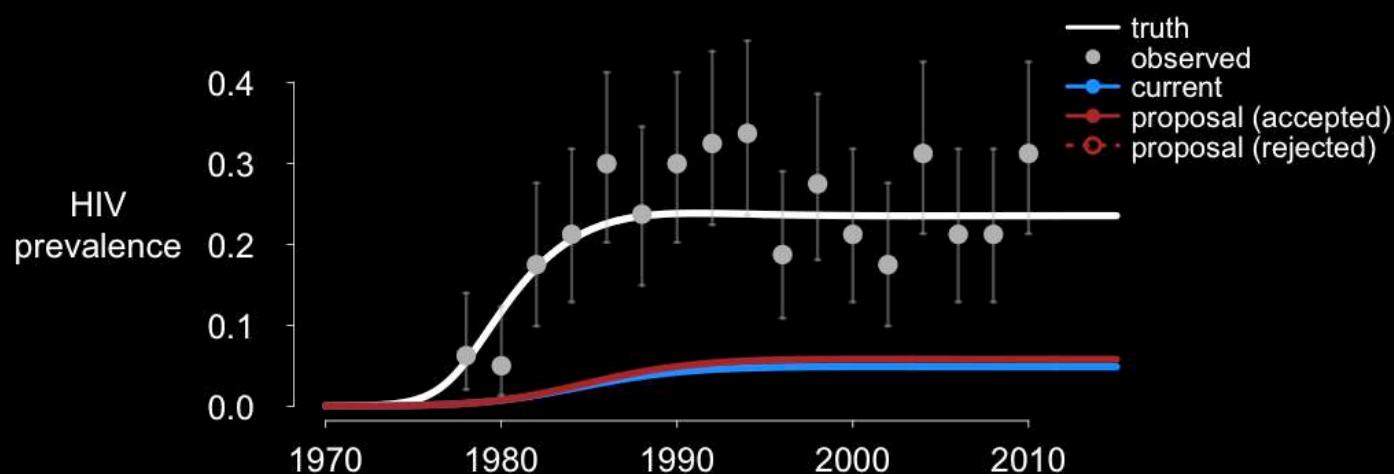
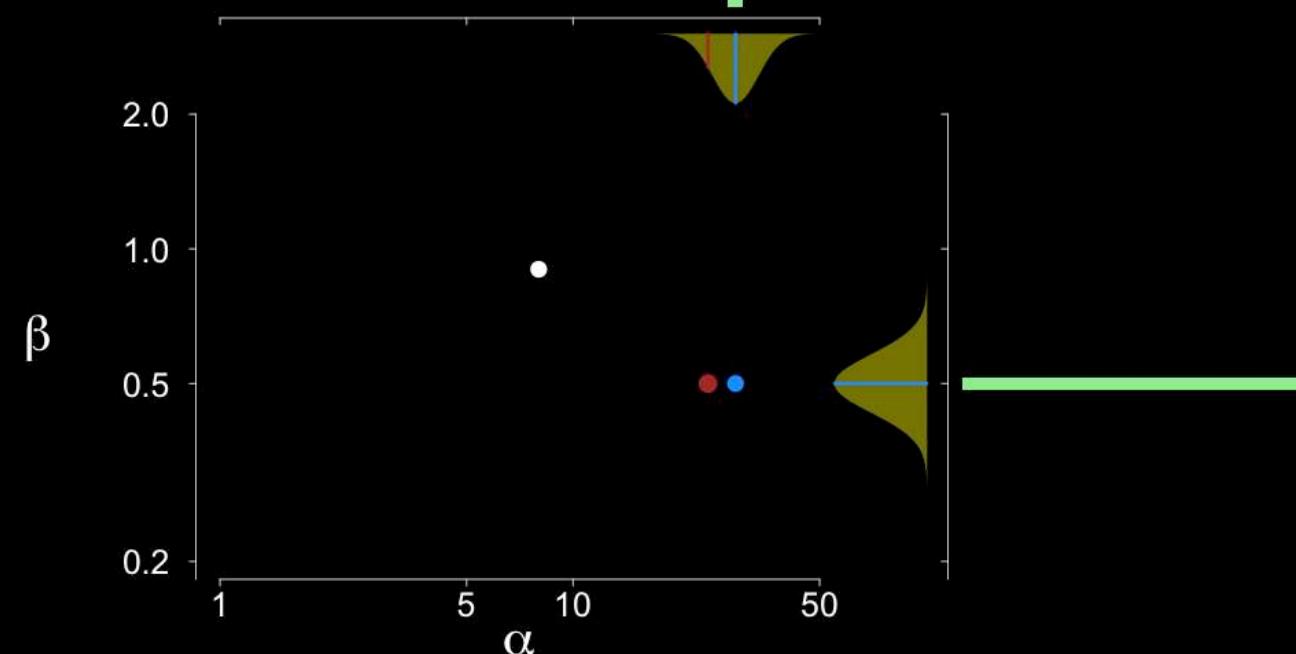


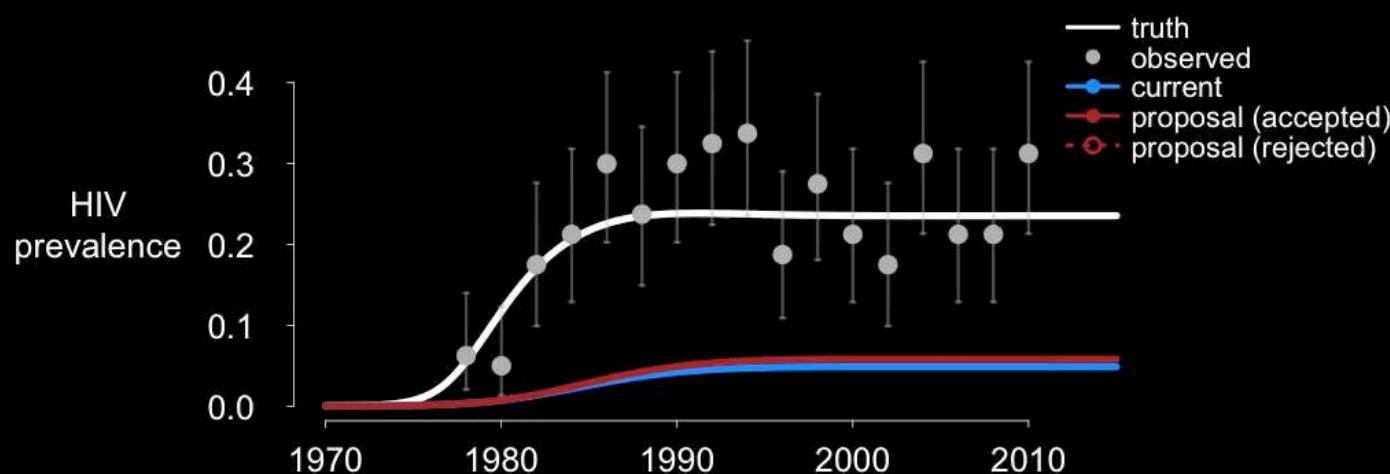
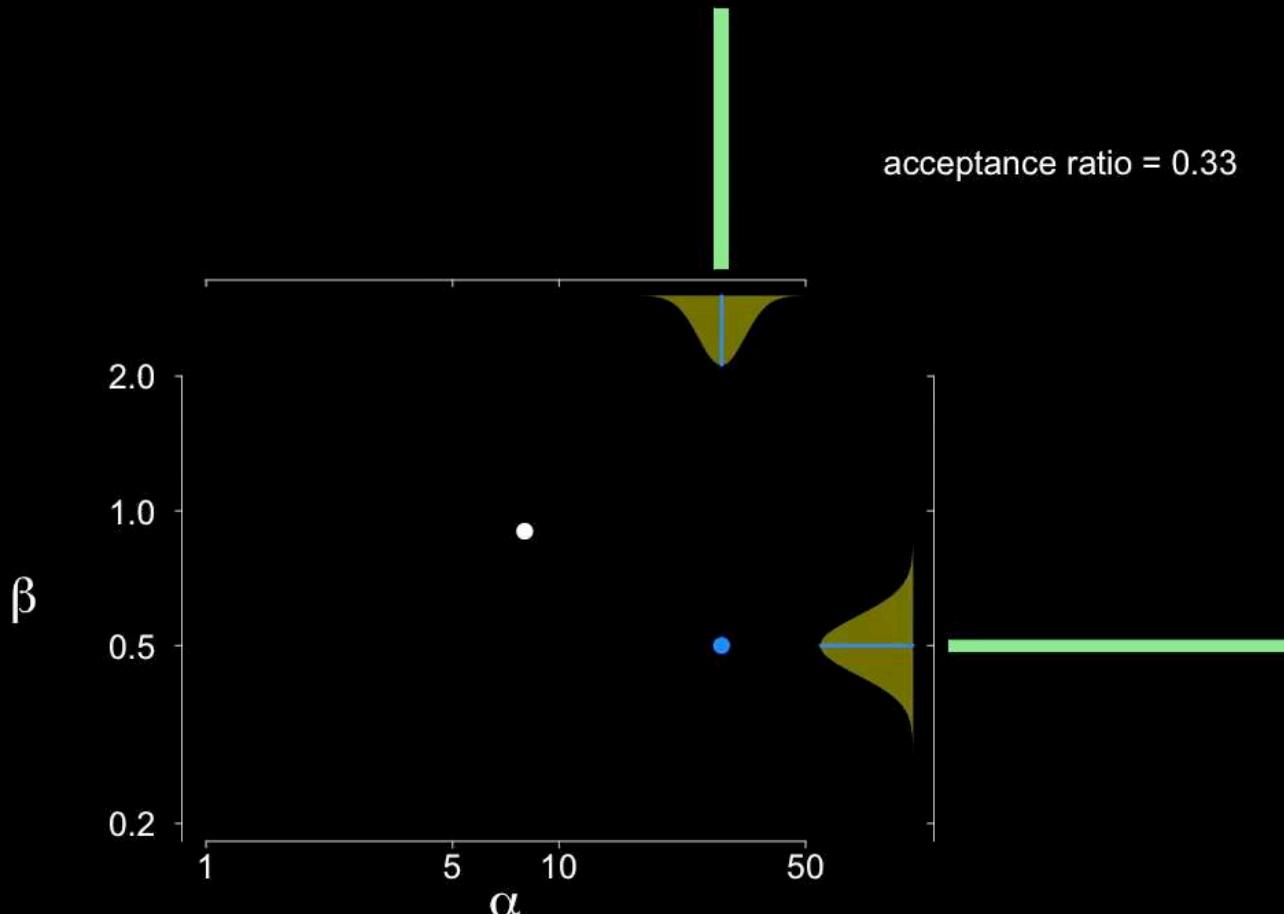
Accept new proposal with probability $\min(\alpha_t, 1)$.

Otherwise stay at same state.



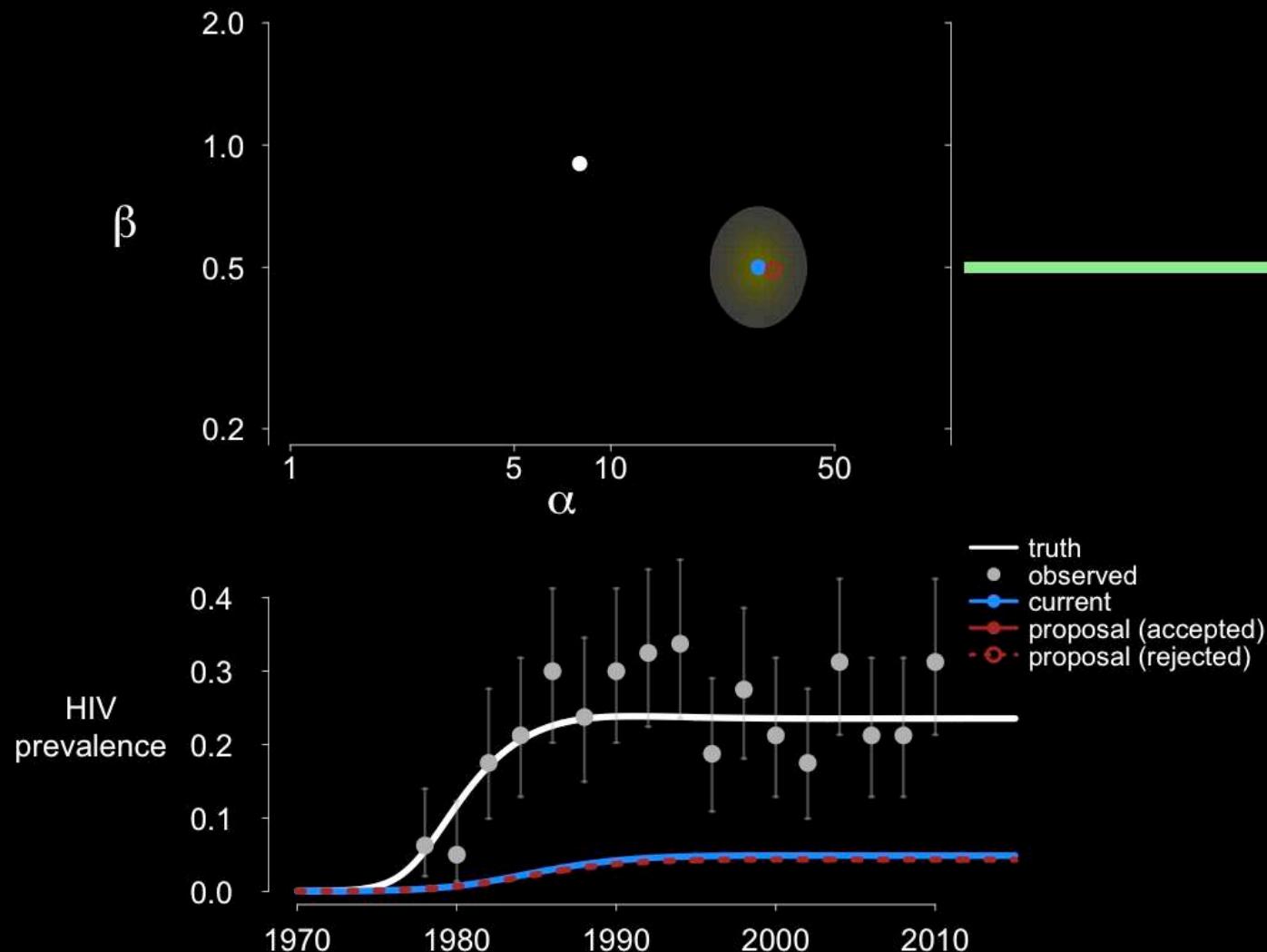
Track distribution of parameter states.





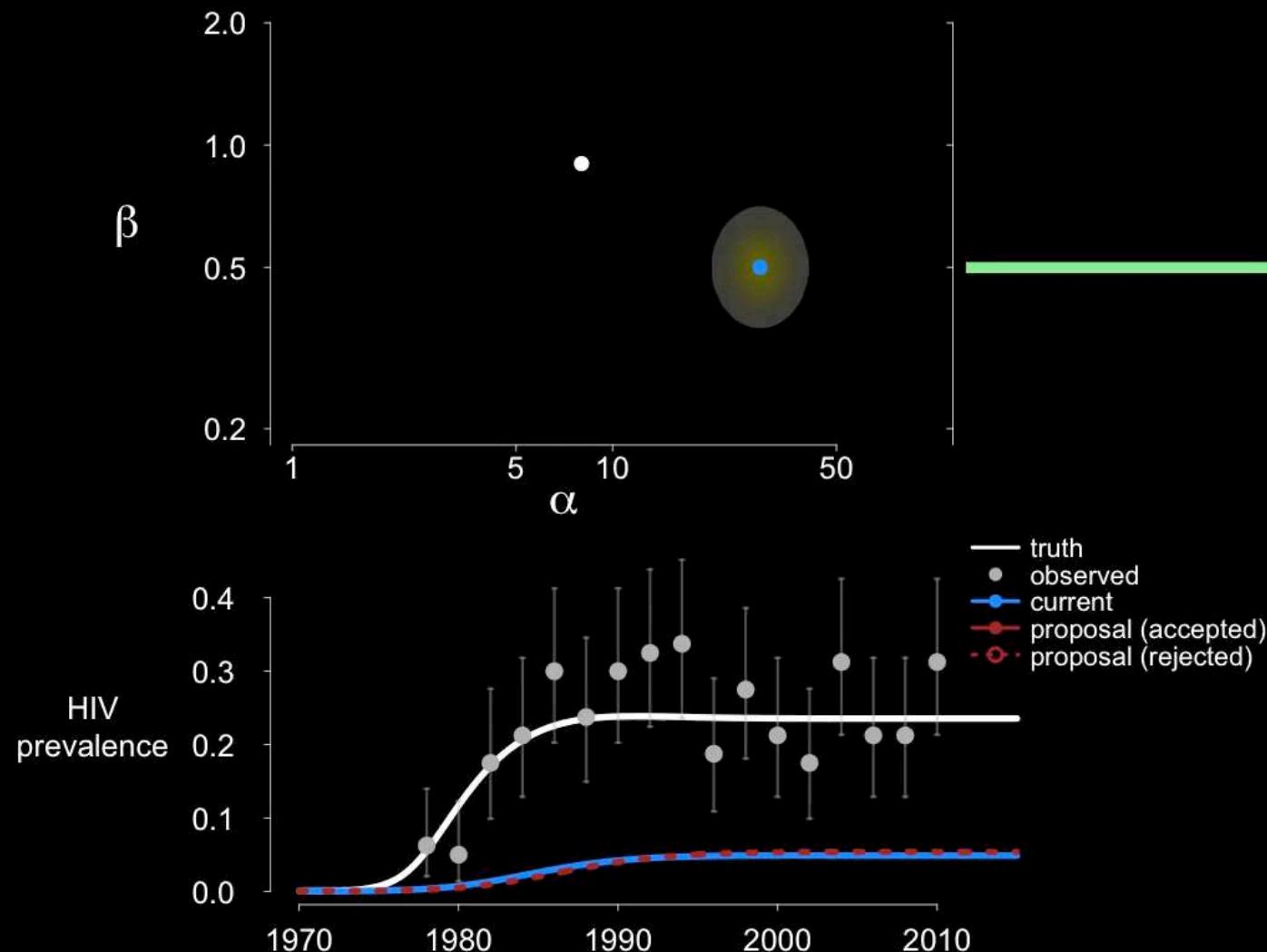
Block proposal distributions allow
diagonal proposals (both parameters
change at once)

acceptance ratio = 0.00



Adaptive block proposals change to
match the posterior more closely
and search more effectively.

acceptance ratio = 0.00



Multivariate MCMC

- Gelman-Rubin diagnostic assesses univariate & multivariate convergence
- Assess trace plots of all parameters
- Block sampling of collinear parameters increases efficiency
- Finding a “good” first guess more challenging for greater # parameters fit

Acceptance Ratio

- Ideal rate is 50% for 1-dimensional fitting
- Approaches 23% for N-dimensional fitting

MCMC Algorithms

- Metropolis-Hastings
 - Gibbs Sampler
 - Hamiltonian MCMC
 - No U-turn Sampler
-
- Block Sampling
 - Adaptive MCMC

More info at

<http://www.bayesian-inference.com/mcmc>

Moving Past MCMC

- Approximate Bayesian Computation

Match data characteristics, rather than explicit likelihoods

- Particle Filters

Fit process noise and observation noise

- Particle MCMC

Combine both approaches



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